



# SGM51613S8

## 8-Channel, 16-Bit, Bipolar Input Simultaneous Sampling ADC

### GENERAL DESCRIPTION

The SGM51613S8 is a 16-bit, 8-channel simultaneous sampling, high-precision successive approximation (SAR) analog-to-digital converter (ADC).

This ADC is powered by a single unipolar 5V, and supports true bipolar  $\pm 10V$  and  $\pm 5V$  inputs. The input range is configured by hardware pin.

The chip provides over-voltage protection up to  $\pm 20V$  at the input.

The chip has an on-chip high accuracy and low drift 8ppm/ $^{\circ}C$  reference.

The input impedance of the chip is  $1M\Omega$  and it is independent of the input range selection.

The ADC supports both high-speed serial and parallel interfaces.

The SGM51613S8 is available in a Green LQFP-10 $\times$ 10-64L package. It is specified from  $-40^{\circ}C$  to  $+125^{\circ}C$ .

### FEATURES

- **8 Channels Simultaneous Sampling**
  - ◆ Support 800kSPS on All Channels Simultaneously
- **True Bipolar Analog Input Ranges:  $\pm 10V$ ,  $\pm 5V$**
- **Single 5V Analog Supply and 2.7V to 5V  $V_{DRIVE}$**
- **Input Buffer with  $1M\Omega$  Analog Input Impedance**
- **On-Chip Accurate Reference and Reference Buffer**
- **Configurable Oversampling Capability with Digital Filter**
- **Flexible Parallel Interface or Serial Interface**
  - ◆ SPI-Compatible
- **Performance**
  - ◆ SNR: 87.4dB (TYP)
  - ◆ THD: -96dB (TYP)
  - ◆ INL:  $\pm 2.5LSB$  (TYP)
  - ◆ DNL:  $+1.8LSB/-0.85LSB$  (TYP)
  - ◆ 7kV ESD Rating on Analog Input Channels
- **Operating Temperature Range:  $-40^{\circ}C$  to  $+125^{\circ}C$**
- **Available in a Green LQFP-10 $\times$ 10-64L Package**

### APPLICATIONS

Power-Line Monitoring and Protection Systems  
Instrumentation and Control Systems  
Multi-Axis Sensor Systems

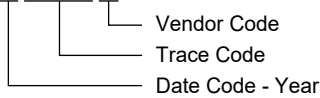
**PACKAGE/ORDERING INFORMATION**

MODEL	PACKAGE DESCRIPTION	SPECIFIED TEMPERATURE RANGE	ORDERING NUMBER	PACKAGE MARKING	PACKING OPTION
SGM51613S8	LQFP-10×10-64L	-40°C to +125°C	SGM51613S8XLFH64G/TR	SGM51613S8 XLFH64 XXXXX	Tape and Reel, 1500
			SGM51613S8XLFH64SG/TR	SGM51613S8 XLFH64 XXXXX	Tape and Reel, 250

**MARKING INFORMATION**

NOTE: XXXXX = Date Code, Trace Code and Vendor Code.

**XXXXX**



Green (RoHS & HSF): SG Micro Corp defines "Green" to mean Pb-Free (RoHS compatible) and free of halogen substances. If you have additional comments or questions, please contact your SGMICRO representative directly.

**ABSOLUTE MAXIMUM RATINGS**

AV <sub>CC</sub> to AGND .....	-0.3V to 6V
V <sub>DRIVE</sub> to AGND.....	-0.3V to AV <sub>CC</sub> + 0.3V
Analog Input Voltage to AGND <sup>(1)</sup> .....	±20V
Digital Input Voltage to AGND .....	-0.3V to V <sub>DRIVE</sub> + 0.3V
Digital Output Voltage to AGND.....	-0.3V to V <sub>DRIVE</sub> + 0.3V
REFIN to AGND.....	-0.3V to AV <sub>CC</sub> + 0.3V
Input Current to Any Pin except Supplies <sup>(1)</sup> .....	±10mA
Package Thermal Resistance	
LQFP-10×10-64L, θ <sub>JA</sub> .....	42.2°C/W
LQFP-10×10-64L, θ <sub>JB</sub> .....	23.2°C/W
LQFP-10×10-64L, θ <sub>JC</sub> .....	8.1°C/W
Junction Temperature.....	+150°C
Storage Temperature Range .....	-65°C to +150°C
Lead Temperature (Soldering, 10s).....	+260°C
ESD Susceptibility	
HBM (Analog Input Pins Only).....	7000V
HBM (All Pins except Analog Inputs) .....	3000V
CDM .....	1000V

NOTE:

1. Transient currents of up to 100mA do not cause SCR latch-up.

**RECOMMENDED OPERATING CONDITIONS**

Operating Temperature Range .....	-40°C to +125°C
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**OVERSTRESS CAUTION**

Stresses beyond those listed in Absolute Maximum Ratings may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect reliability. Functional operation of the device at any conditions beyond those indicated in the Recommended Operating Conditions section is not implied.

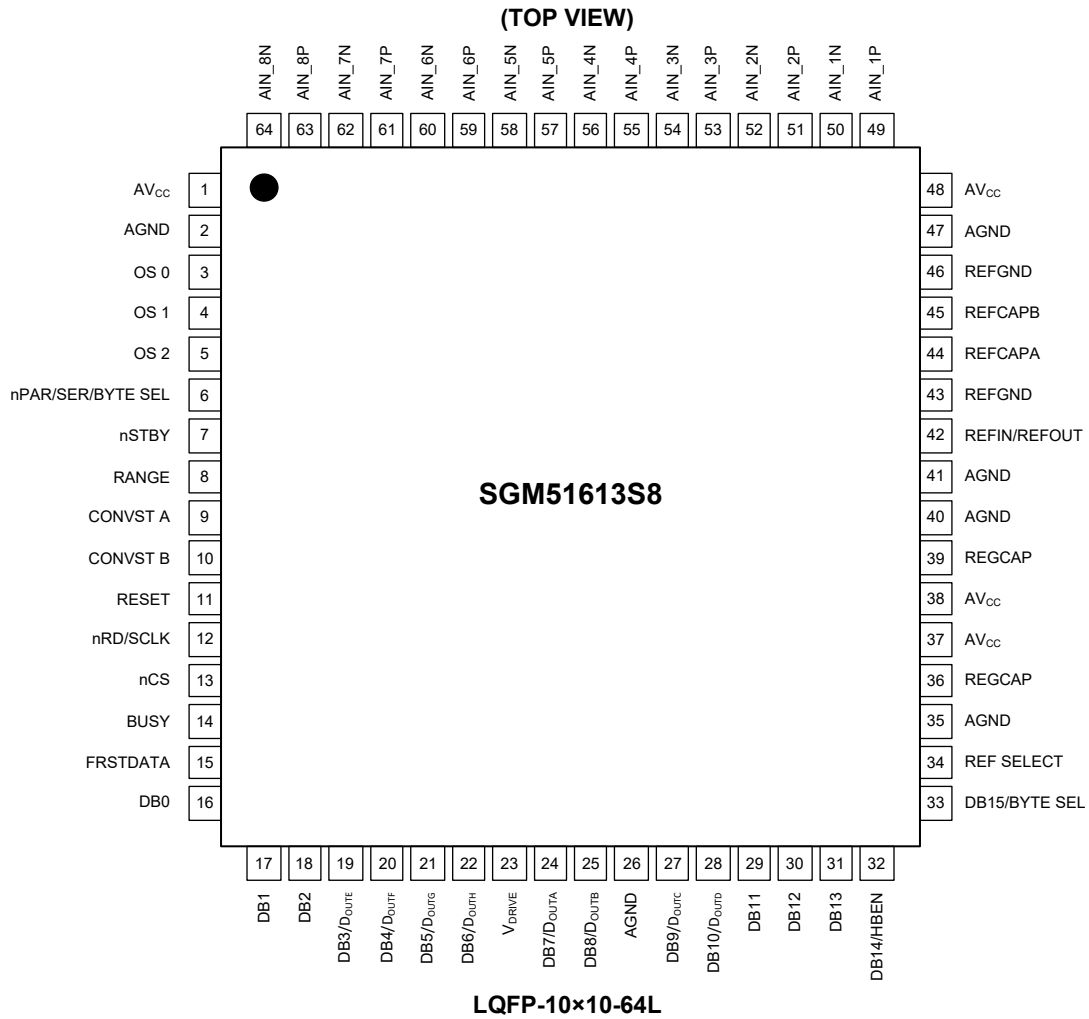
**ESD SENSITIVITY CAUTION**

This integrated circuit can be damaged if ESD protections are not considered carefully. SGMICRO recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage. ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because even small parametric changes could cause the device not to meet the published specifications.

**DISCLAIMER**

SG Micro Corp reserves the right to make any change in circuit design, or specifications without prior notice.

PIN CONFIGURATION



## PIN DESCRIPTION

PIN	NAME	TYPE	FUNCTION
1, 37, 38, 48	AV <sub>CC</sub>	P	Analog Power Supply Pin. It is the power supply of analog front end and ADC core circuit.
2, 26, 35, 40, 41, 47	AGND	P	Analog Ground Pin. All AGND pins must share the same system connection plane.
3	OS 0	DI	Oversampling Mode Setting Pins. They are logic input control pins. More details please refer to Table 4.
4	OS 1		
5	OS 2		
6	nPAR/SER/ BYTE SEL	DI	Parallel/Serial/Byte Interface Setting Pin. It is a logic input. If it is set to logic low, the parallel interface is enabled. If it is set to logic high, the serial interface is enabled. To select byte parallel interface, set the pin and DB15/BYTE SEL pin to logic high at the same time for a combined enable controlling (refer to Table 3).  If the chip works in serial mode, the nRD/SCLK pin is the serial interface clock input pin. The DB7/D <sub>OUTA</sub> pin and DB8/D <sub>OUTB</sub> pin are combined together as two lane serial interface data output pins. The DB[15:9] and DB[6:0] pins should be connected to GND.  If the chip works in byte parallel interface mode, DB14 is used as the HBEN pin. DB[7:0] is read out in two nRD read frame. The data format is high byte first.
7	nSTBY	DI	Standby Mode Setting Input Pin. This pin is a logic input pin. It works with the RANGE pin together to determine whether the chip is going to enter standby mode or shutdown mode. More details please refer to Table 2.
8	RANGE	DI	Analog Input Range Setting Pin. This pin is a logic input pin. If it is set to logic high, the analog input range $\pm 10V$ is set for all channels. If it is set to logic low, the analog input range $\pm 5V$ is set for all channels. Any change on the logic of the input range setting pin takes effect immediately. It is strongly not recommended to change the input range during a conversion or a consequences inputs scanning.
9	CONVST A	DI	Conversion Start Input Pin A and Conversion Start Input Pin B. They are logic input pins. When the input logic from low to high, the input tracking and holding circuitry stops sampling and changes to hold, and the ADC initiates a conversion.  CONVST A and CONVST B can be tied together for all channels sampling simultaneously.  When the oversampling function is not enabled, CONVST A and CONVST B can be used to control ADC conversion separately. CONVST A can be used to control channel V1, V2, V3 and V4. CONVST B can be used to control channel V5, V6, V7 and V8.
10	CONVST B		
11	RESET	DI	Reset Input Pin. An input from logic low to logic high, the rising edge of the input signal triggers the reset action, and the high pulse must be held at least 50ns.  Reset input will terminate the ongoing ADC conversion. And the reset input also will set the ADC output registers to all zero.
12	nRD/SCLK	DI	Multi-Function Pin nRD/SCLK. When the chip is in parallel interface mode, the nRD/SCLK is active logic low. When the chip is in serial interface mode, the nRD/SCLK is active logic low. The data on data bus are locked out on the rising edge of SCLK. For more information, see the Conversion Control section.
13	nCS	DI	Chip Select Control Pin. This pin is active logic low. In serial interface mode, the nCS is used as data frame signal, and the MSB of the serial output is shifted out on the falling edge of nCS.
14	BUSY	DO	Busy Indicator Output Pin. If there is a trigger rising edge of CONVST A or CONVST B, this BUSY pin goes to high immediately. It does not go to low until all the channels conversions have been completed. The falling edge of the BUSY pin indicates that the conversion results are ready to read (it needs a reasonable time delay $t_4$ ).  Any data read operation must be finished before the next falling edge of BUSY coming. During the high of BUSY, any ADC trigger signals of CONVST A and CONVST B are ignored.

## PIN DESCRIPTION (continued)

PIN	NAME	TYPE	FUNCTION
15	FRSTDATA	DO	Digital Indicator Output Pin. This pin is active high. In parallel interface mode, the falling edge of nRD which is corresponded to read V1 channel sets the FRSTDATA pin high, and the next following edge of nRD sets the FRSTDATA pin low. In serial interface mode, the falling edge of nCS sets the FRSTDATA pin high. In the same read operation frame, the 16 <sup>th</sup> SCLK falling edge sets the FRSTDATA pin low. If nCS is high, the FRSTDATA pin is in three-state.
16, 17, 18	DB0, DB1, DB2	DO	Parallel Interface Output Data Bits. In serial interface mode, these pins should be connected to AGND.
19	DB3/D <sub>OUTE</sub>	DO	Multi-Function Pin, Parallel Interface Output Data Bit 3 (DB3)/Serial Interface Data Output Pin (D <sub>OUTE</sub> ). In parallel interface mode, this pin works as DB3. In serial interface mode, this pin works as D <sub>OUTE</sub> .
20	DB4/D <sub>OUTF</sub>	DO	Multi-Function Pin, Parallel Interface Output Data Bit 4 (DB4)/Serial Interface Data Output Pin (D <sub>OUTF</sub> ). In parallel interface mode, this pin works as DB4. In serial interface mode, this pin works as D <sub>OUTF</sub> .
21	DB5/D <sub>OUTG</sub>	DO	Multi-Function Pin, Parallel Interface Output Data Bit 5 (DB5)/Serial Interface Data Output Pin (D <sub>OUTG</sub> ). In parallel interface mode, this pin works as DB5. In serial interface mode, this pin works as D <sub>OUTG</sub> .
22	DB6/D <sub>OUTH</sub>	DO	Multi-Function Pin, Parallel Interface Output Data Bit 6 (DB6)/Serial Interface Data Output Pin (D <sub>OUTH</sub> ). In parallel interface mode, this pin works as DB6. In serial interface mode, this pin works as D <sub>OUTH</sub> .
23	V <sub>DRIVE</sub>	P	Login Interface Power Supply Pin.
24	DB7/D <sub>OUTA</sub>	DO	Multi-Function Pin, Parallel Interface Output Data Bit 7 (DB7)/Serial Interface Data Output Pin (D <sub>OUTA</sub> ). In parallel interface mode, this pin works as DB7. In serial interface mode, this pin works as D <sub>OUTA</sub> .
25	DB8/D <sub>OUTB</sub>	DO	Multi-Function Pin, Parallel Interface Output Data Bit 8 (DB8)/Serial Interface Data Output Pin (D <sub>OUTB</sub> ). In parallel interface mode, this pin works as DB8. In serial interface mode, this pin works as D <sub>OUTB</sub> .
27	DB9/D <sub>OUTC</sub>	DO	Multi-Function Pin, Parallel Interface Output Data Bit 9 (DB9)/Serial Interface Data Output Pin (D <sub>OUTC</sub> ). In parallel interface mode, this pin works as DB9. In serial interface mode, this pin works as D <sub>OUTC</sub> .
28	DB10/D <sub>OUTD</sub>	DO	Multi-Function Pin, Parallel Interface Output Data Bit 10 (DB10)/Serial Interface Data Output Pin (D <sub>OUTD</sub> ). In parallel interface mode, this pin works as DB10. In serial interface mode, this pin works as D <sub>OUTD</sub> .
29, 30, 31	DB11, DB12, DB13	DO	Parallel Interface Output Data Bits. In byte parallel interface mode and serial interface mode (nPAR/SER/BYTE SEL = 1), these pins should be connected to AGND.

## PIN DESCRIPTION (continued)

PIN	NAME	TYPE	FUNCTION
32	DB14/HBEN	DO/DI	Multi-Function Pin, Parallel Interface Output Data Bit 14 (DB14)/High Byte Enable (HBEN). In parallel interface mode, this pin works as DB14. In parallel byte interface mode, this pin is used to select if the most significant byte (MSB) or the least significant byte (LSB) of the data is output first. If HBEN is set to high, MSB is output first. If HBEN is set to low, LSB is output first. In serial mode, this pin should be tied to GND.
33	DB15/ BYTE SEL	DO/DI	Multi-Function Pin, Parallel Interface Output Data Bit 15 (DB15)/Parallel Interface Byte Mode Select (BYTE SEL). In parallel interface mode, this pin works as DB15. If nPAR/SER/BYTE SEL is set to high and DB15/BYTE SEL is set to low, the chip works in serial interface mode. If nPAR/SER/BYTE SEL is set to high and DB15/BYTE SEL is set to high, the chip works in parallel byte interface mode.
34	REF SELECT	DI	Internal/External Reference Selection Pin. This is a logic input pin. If it is set to logic high, the internal reference is enabled. If it is set to logic low, an external reference must be connected to the chip.
36, 39	REGCAP	P	Internal Regulator Decoupling Pins. Each pin needs a separate 1 $\mu$ F decoupling capacitor connected to AGND.
42	REFIN/REFOUT	REF	Reference Input Pin (REFIN)/Reference Output Pin (REFOUT). A 10 $\mu$ F decoupling capacitor needs to be connected between this pin and REFGND.
43, 46	REFGND	REF	Reference Ground Pins. These pins should be connected to AGND.
44, 45	REFCAPA, REFCAPB	REF	Reference Buffer Output Sense Pins. These pins must be tied together. A 10 $\mu$ F decoupling capacitor needs to be connected between these pins and AGND.
49	AIN_1P	AI	Channel 1 Positive Analog Input.
50	AIN_1N	AI	Channel 1 Negative Analog Input.
51	AIN_2P	AI	Channel 2 Positive Analog Input.
52	AIN_2N	AI	Channel 2 Negative Analog Input.
53	AIN_3P	AI	Channel 3 Positive Analog Input.
54	AIN_3N	AI	Channel 3 Negative Analog Input.
55	AIN_4P	AI	Channel 4 Positive Analog Input.
56	AIN_4N	AI	Channel 4 Negative Analog Input.
57	AIN_5P	AI	Channel 5 Positive Analog Input.
58	AIN_5N	AI	Channel 5 Negative Analog Input.
59	AIN_6P	AI	Channel 6 Positive Analog Input.
60	AIN_6N	AI	Channel 6 Negative Analog Input.
61	AIN_7P	AI	Channel 7 Positive Analog Input.
62	AIN_7N	AI	Channel 7 Negative Analog Input.
63	AIN_8P	AI	Channel 8 Positive Analog Input.
64	AIN_8N	AI	Channel 8 Negative Analog Input.

NOTE: P = power supply, DI = digital input, DO = digital output, REF = reference input/output, AI = analog input.

**ELECTRICAL CHARACTERISTICS**

(V<sub>REF</sub> = 2.5V external/internal, AV<sub>CC</sub> = 4.75V to 5.25V, V<sub>DRIVE</sub> = 2.7V to 5.25V, f<sub>SAMPLE</sub> = 800kSPS, T<sub>A</sub> = -40°C to +125°C, typical values are at T<sub>A</sub> = +25°C, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
<b>Dynamic Performance (f<sub>IN</sub> = 1kHz sine wave, unless otherwise noted)</b>							
Signal-to-Noise Ratio <sup>(1)</sup>	SNR	Oversampling by 16, ±10V range, f <sub>IN</sub> = 130Hz		87	91.6		dB
		Oversampling by 16, ±5V range, f <sub>IN</sub> = 130Hz		86.4	90.9		
		No oversampling, ±10V range		82.6	87.4		
		No oversampling, ±5V range		81.6	86.4		
Signal-to-Noise + Distortion	SINAD	No oversampling, ±10V range		82.2	86.9		dB
		No oversampling, ±5V range		81.2	85.9		
Dynamic Range		No oversampling, ±10V range			98.5		dB
		No oversampling, ±5V range			97.5		
		Oversampling by 16, ±10V range			106		
		Oversampling by 16, ±5V range			105		
Total Harmonic Distortion	THD				-96		dB
Spurious Free Dynamic Range	SFDR				-100		dB
Intermodulation Distortion	IMD	f <sub>A</sub> = 1kHz, f <sub>B</sub> = 1.1kHz	Second-order terms		-113		dB
			Third-order terms		-116		
Channel-to-Channel Isolation		f <sub>IN</sub> on unselected channels up to 160kHz			-100		dB
<b>Analog Input Filter</b>							
Full Power Bandwidth	BW	-3dB	±10V range		96		kHz
			±5V range		96		
		-0.1dB	±10V range		16		
			±5V range		16		
<b>DC Accuracy</b>							
Resolution		No missing codes		16			Bits
Integral Nonlinearity <sup>(2)</sup>	INL			-5	±2.5	5	LSB
Differential Nonlinearity	DNL			-0.99	+1.8/-0.85	3.5	LSB <sup>(3)</sup>
Total Unadjusted Error	TUE	±10V range			±22		LSB
		±5V range			±22		
Positive Full-Scale Error <sup>(4)</sup>		External reference			±20	66	LSB
		Internal reference			±20	130	
Positive Full-Scale Error Drift		External reference			2		ppm/°C
		Internal reference			10		
Positive Full-Scale Error Matching		±10V range			10	32	LSB
		±5V range			10	32	
Bipolar Zero-Code Error <sup>(5)</sup>		±10V range			±1	12	LSB
		± 5V range			±1	12	
Bipolar Zero-Code Error Drift		±10V range			6		µV/°C
		± 5V range			4		
Bipolar Zero-Code Error Matching		±10V range			2	12	LSB
		±5V range			3	12	

**ELECTRICAL CHARACTERISTICS (continued)**

( $V_{REF} = 2.5V$  external/internal,  $AV_{CC} = 4.75V$  to  $5.25V$ ,  $V_{DRIVE} = 2.7V$  to  $5.25V$ ,  $f_{SAMPLE} = 800kSPS$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ , typical values are at  $T_A = +25^{\circ}C$ , unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Negative Full-Scale Error <sup>(4)</sup>		External reference		±20	66	LSB
		Internal reference		±20	130	
Negative Full-Scale Error Drift		External reference		2		ppm/°C
		Internal reference		10		
Negative Full-Scale Error Matching		±10V range		10	32	LSB
		±5V range		10	32	
<b>Analog Input</b>						
Input Voltage Ranges	$V_{IN}$	RANGE = 1			±10	V
		RANGE = 0			±5	
Analog Input Current		10V		7.0		μA
		5V		2.6		
Input Capacitance <sup>(6)</sup>	$C_{IN}$			5		pF
Input Impedance	$R_{IN}$	See the Analog Input section		1		MΩ
<b>Input Over-Voltage Protection</b>						
Over-Voltage Protection Voltage	$V_{OVP}$	$AV_{CC} = 5V$ , all input ranges	-20		20	V
		$AV_{CC} =$ floating, all input ranges	-11		11	V
<b>Reference Input/Output</b>						
Reference Input Voltage Range	$V_{REF}$	See the ADC Transfer Function section	2.475	2.5	2.525	V
DC Leakage Current				0.02	0.5	μA
Input Capacitance <sup>(6)</sup>		REF SELECT = 1		6		pF
Reference Output Voltage		REFIN/REFOUT		2.5		V
Reference Temperature Coefficient <sup>(7)</sup>				8		ppm/°C
<b>Logic Inputs</b>						
Input High Voltage	$V_{IH}$		$0.8 \times V_{DRIVE}$			V
Input Low Voltage	$V_{IL}$				$0.2 \times V_{DRIVE}$	V
Input Current	$I_{IN}$			±0.1	1	μA
Input Capacitance <sup>(6)</sup>	$C_{IN}$			5		pF
<b>Logic Outputs</b>						
Output High Voltage	$V_{OH}$	$I_{SOURCE} = 100\mu A$	$V_{DRIVE} - 0.2$			V
Output Low Voltage	$V_{OL}$	$I_{SINK} = 100\mu A$			0.2	V
Floating-State Leakage Current				±0.1	1	μA
Floating-State Output Capacitance <sup>(6)</sup>				5		pF
Output Coding			Two's complement			
<b>Conversion Rate</b>						
Conversion Time	$t_{CONV}$	All eight channels included		0.95		μs
Track-and-Hold Acquisition Time	$t_{ACQ}$	All eight channels included		0.3		μs
Throughput Rate		All eight channels included			800	kSPS



**ELECTRICAL CHARACTERISTICS (continued)**

( $V_{REF} = 2.5V$  external/internal,  $AV_{CC} = 4.75V$  to  $5.25V$ ,  $V_{DRIVE} = 2.7V$  to  $5.25V$ ,  $f_{SAMPLE} = 800kSPS$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ , typical values are at  $T_A = +25^{\circ}C$ , unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
<b>Power Requirements</b>							
Analog Supply Voltage	$AV_{CC}$		4.75		5.25	V	
Digital I/O Supply Voltage	$V_{DRIVE}$		2.7		$AV_{CC}$	V	
Supply Current	$I_{TOTAL}$	Digital inputs = 0V or $V_{DRIVE}$	Normal mode (static)		22.2	35	mA
			Normal mode (operational) <sup>(8)</sup> , $f_{SAMPLE} = 800kSPS$		54	68	mA
			Standby mode		8.9	14	mA
			Shutdown mode		15	40	$\mu A$
<b>Power Dissipation</b>							
Power Dissipation	$P_D$	Normal mode (static)		111	184	mW	
		Normal mode (operational) <sup>(8)</sup> , $f_{SAMPLE} = 800kSPS$		270	357	mW	
		Standby mode		45	74	mW	
		Shutdown mode		75	210	$\mu W$	

## NOTES:

1. This applies to read during a conversion or after a conversion. When reading during a conversion in parallel mode, the SNR is typically reduced by 2dB and THD by 1dB.
2. This is best-fit INL.
3. LSB = Least Significant Bit. 1LSB =  $152.58\mu V$  in the  $\pm 5V$  input range. 1LSB =  $305.175\mu V$  in the  $\pm 10V$  input range.
4. These include the full temperature range variation and contribution from the internal reference buffer, but exclude the error contribution from the external reference.
5. Bipolar zero-code error is calculated with respect to the analog input voltage. Refer to the Analog Input Clamp Protection section.
6. Test samples at initial release to ensure compliance.
7. The way to determine temperature drift is the box method.
8. The operational power/current figure includes the contribution when operating in oversampling mode.

**TIMING SPECIFICATIONS**

(AV<sub>CC</sub> = 4.75V to 5.25V, V<sub>DRIVE</sub> = 2.7V to 5.25V, V<sub>REF</sub> = 2.5V external reference/internal reference, T<sub>A</sub> = -40°C to +125°C, unless otherwise noted.)<sup>(1)</sup>

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>Parallel/Serial/Byte Mode</b>						
1/Throughput Rate	t <sub>4</sub> /t <sub>CYCLE</sub>	Parallel mode, reading during or after conversion: V <sub>DRIVE</sub> = 2.7V to 5.25V; serial mode, reading during conversion: D <sub>OUTA</sub> , D <sub>OUTB</sub> , D <sub>OUTC</sub> , D <sub>OUTD</sub> , D <sub>OUTE</sub> , D <sub>OUTF</sub> , D <sub>OUTG</sub> and D <sub>OUTH</sub> lines, V <sub>DRIVE</sub> = 2.7V to 5.25V			1.25	μs
		Serial mode, reading after a conversion, V <sub>DRIVE</sub> = 4.75V to 5.25V			1.5	
		Serial mode, reading after a conversion, V <sub>DRIVE</sub> = 3.3V			1.75	
		Serial mode, reading after a conversion, V <sub>DRIVE</sub> = 2.7V			1.85	
Conversion Time	t <sub>CONV</sub>	Oversampling off	0.7	0.85	0.95	μs
		Oversampling by 2	1.65	1.9	2.15	
		Oversampling by 4	3.75	4.0	4.2	
		Oversampling by 8	7.8	8.2	8.6	
		Oversampling by 16	16.00	16.60	17.20	
		Oversampling by 32	32.00	33.40	34.20	
		Oversampling by 64	65.00	67.00	69.00	
nSTBY Rising Edge to CONVST x Rising Edge, Power-Up Time from Standby Mode	t <sub>WAKE-UP STANDBY</sub>			200		μs
nSTBY Rising Edge to CONVST x Rising Edge, Power-Up Time from Shutdown Mode	t <sub>WAKE-UP SHUTDOWN</sub>	Internal reference		23		ms
		External reference		20		
RESET High Pulse Width	t <sub>1</sub>		50			ns
BUSY to OS x Pin Setup Time	t <sub>OS_SETUP</sub>		50			ns
BUSY to OS x Pin Hold Time	t <sub>OS_HOLD</sub>		25			ns
CONVST x High to BUSY High	t <sub>6</sub>				40	ns
Minimum CONVST x Low Pulse	t <sub>3</sub>		25			ns
Minimum CONVST x High Pulse	t <sub>5</sub>		25			ns
BUSY Falling Edge to nCS Falling Edge Setup Time	t <sub>7</sub>		0			ns
Maximum Delay Allowed between CONVST A and CONVST B Rising Edges <sup>(2)</sup>	t <sub>30</sub>				0.5	ms
Minimum Time between Last nCS Rising Edge and BUSY Falling Edge	t <sub>8</sub>		50			ns
Minimum Delay between RESET Low to CONVST x Low	t <sub>2</sub>		25			ns
<b>Parallel/Byte Read Operation</b>						
nCS to nRD Setup Time	t <sub>9</sub>		0			ns
nCS to nRD Hold Time	t <sub>12</sub>		0			ns
nRD Low Pulse Width	t <sub>10</sub>	V <sub>DRIVE</sub> above 4.75V	16			ns
		V <sub>DRIVE</sub> above 3.3V	20			
		V <sub>DRIVE</sub> above 2.7V	20			

**TIMING SPECIFICATIONS (continued)**

( $V_{CC} = 4.75V$  to  $5.25V$ ,  $V_{DRIVE} = 2.7V$  to  $5.25V$ ,  $V_{REF} = 2.5V$  external reference/internal reference,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ , unless otherwise noted.)<sup>(1)</sup>

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
nRD High Pulse Width	$t_{11}$		14			ns
nCS High Pulse Width, nCS and nRD Linked	$t_{29}$	See Figure 4	16			ns
Delay from nCS until DB[15:0] Three-State Disabled	$t_{13}$	$V_{DRIVE}$ above 4.75V			16	ns
		$V_{DRIVE}$ above 3.3V			20	
		$V_{DRIVE}$ above 2.7V			20	
Data Access Time after nRD Falling Edge <sup>(3)</sup>	$t_{14}$	$V_{DRIVE}$ above 4.75V			16	ns
		$V_{DRIVE}$ above 3.3V			20	
		$V_{DRIVE}$ above 2.7V			20	
Data Hold Time after nRD Falling Edge	$t_{31}$		6			ns
nCS to DB[15:0] Hold Time	$t_{32}$		6			ns
Delay from nCS Rising Edge to DB[15:0] Three-State Enabled	$t_{33}$				25	ns
<b>Serial Read Operation</b>						
Frequency of Serial Read Clock	$f_{SCLK}$	$V_{DRIVE}$ above 4.75V			36	MHz
		$V_{DRIVE}$ above 3.3V			28	
		$V_{DRIVE}$ above 2.7V			25	
Delay from nCS until $D_{OUTx}$ Three-State Disabled/Delay from nCS until MSB Valid	$t_{22}$	$V_{DRIVE}$ above 4.75V			14	ns
		$V_{DRIVE}$ above 3.3V			18	
		$V_{DRIVE}$ above 2.7V			20	
Data Access Time after SCLK Rising Edge <sup>(3)</sup>	$t_{23}$	$V_{DRIVE}$ above 4.75V			14	ns
		$V_{DRIVE}$ above 3.3V			18	
		$V_{DRIVE}$ above 2.7V			20	
SCLK Low Pulse Width	$t_{21}$		$0.4 \times t_{SCLK}$			ns
SCLK High Pulse Width	$t_{20}$		$0.4 \times t_{SCLK}$			ns
SCLK Rising Edge to $D_{OUTx}$ Valid Hold Time	$t_{24}$		6			ns
nCS Rising Edge to $D_{OUTx}$ Three-State Enabled	$t_{25}$				25	ns

**TIMING SPECIFICATIONS (continued)**

( $V_{CC} = 4.75V$  to  $5.25V$ ,  $V_{DRIVE} = 2.7V$  to  $5.25V$ ,  $V_{REF} = 2.5V$  external reference/internal reference,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ , unless otherwise noted.)<sup>(1)</sup>

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>FRSTDATA Operation</b>						
Delay from nCS Falling Edge until FRSTDATA Three-State Disabled	$t_{16}$	$V_{DRIVE}$ above 4.75V			15	ns
		$V_{DRIVE}$ above 3.3V			20	
		$V_{DRIVE}$ above 2.7V			25	
Delay from nCS Falling Edge until FRSTDATA High, Serial Mode	$t_{26}$	$V_{DRIVE}$ above 4.75V			15	ns
		$V_{DRIVE}$ above 3.3V			20	
		$V_{DRIVE}$ above 2.7V			25	
Delay from nRD Falling Edge to FRSTDATA High	$t_{17}$	$V_{DRIVE}$ above 4.75V			15	ns
		$V_{DRIVE}$ above 3.3V			20	
		$V_{DRIVE}$ above 2.7V			25	
Delay from nRD Falling Edge to FRSTDATA Low	$t_{18}$	$V_{DRIVE} = 3.3V$ to $5.25V$			20	ns
		$V_{DRIVE} = 2.7V$ to $3.3V$			30	
Delay from 16 <sup>th</sup> SCLK Falling Edge to FRSTDATA Low	$t_{27}$	$V_{DRIVE} = 3.3V$ to $5.25V$			20	ns
		$V_{DRIVE} = 2.7V$ to $3.3V$			30	
Delay from nCS Rising Edge until FRSTDATA Three-State Enabled	$t_{19}$				25	ns

## NOTES:

- Sample tested during initial release to ensure compliance. All input signals are specified with  $t_R = t_F = 5ns$  (10% to 90% of  $V_{DRIVE}$ ) and timed from a voltage level of 1.6V.
- The delay between the CONVST x signals was measured as the maximum time allowed while ensuring a < 10LSB performance matching between channel sets.
- A buffer is used on the data output pins for these measurements, which is equivalent to a 20pF load on the output pins.

TIMING DIAGRAMS

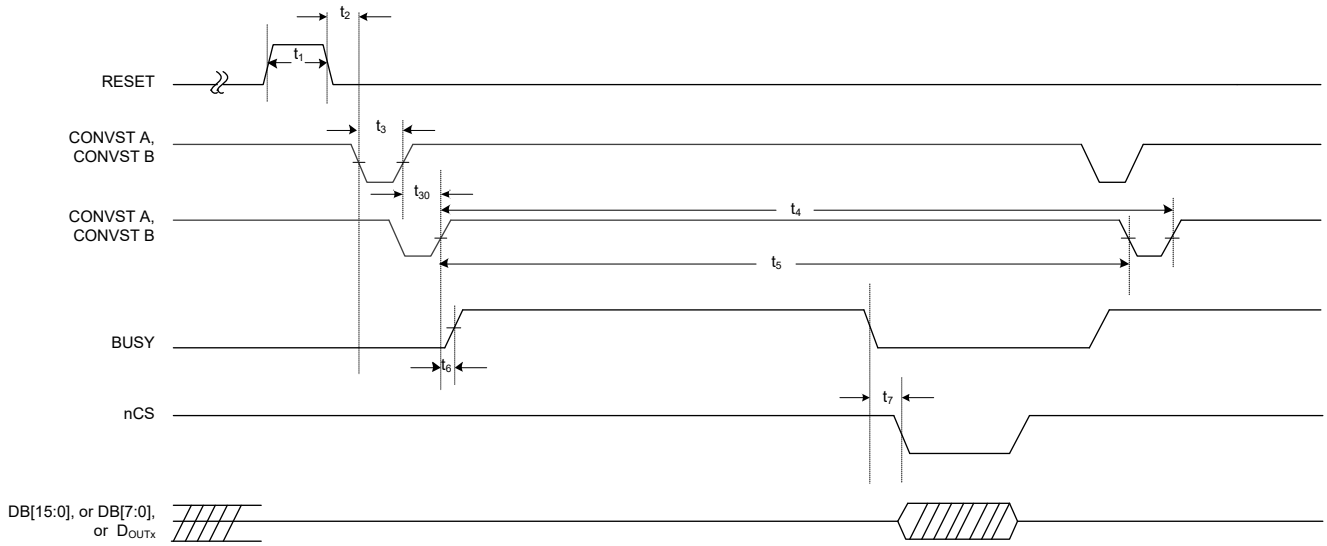


Figure 1. CONVST Timing (Reading after a Conversion)

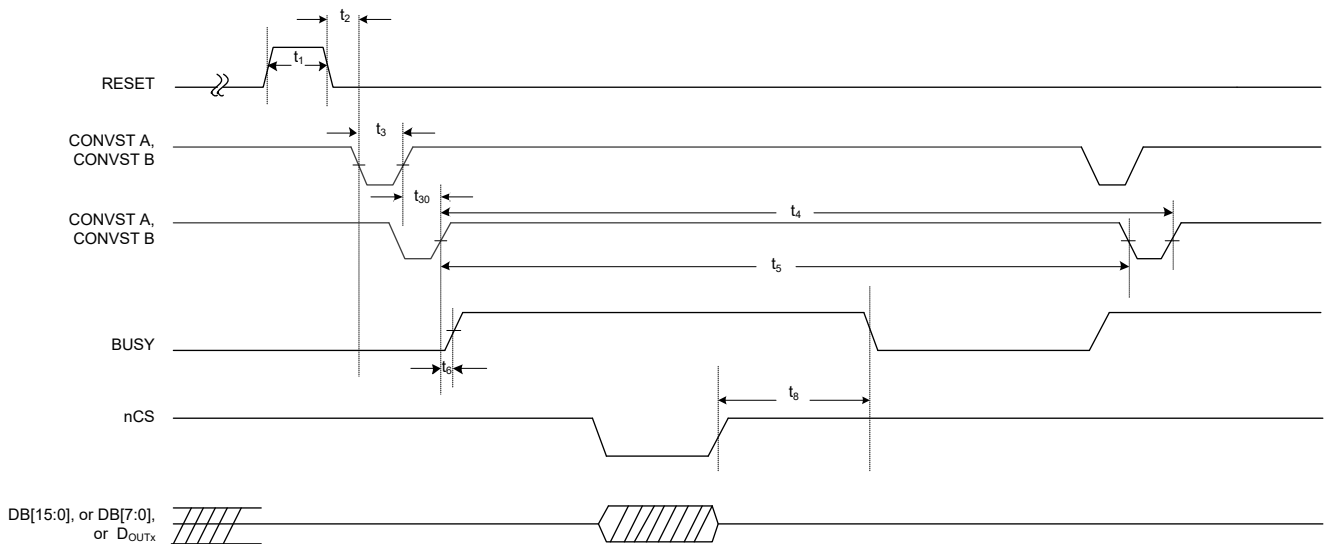


Figure 2. CONVST Timing (Reading during a Conversion)

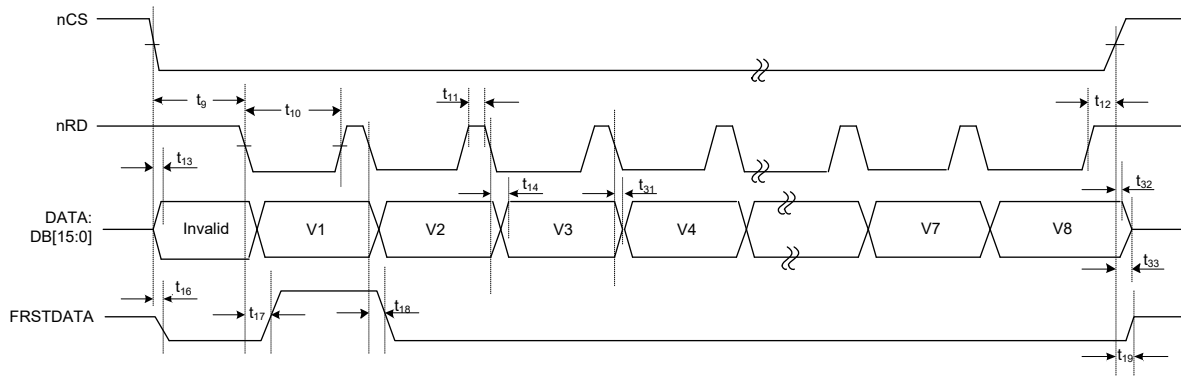


Figure 3. Parallel Mode, Separate nCS and nRD Pulses

TIMING DIAGRAMS (continued)

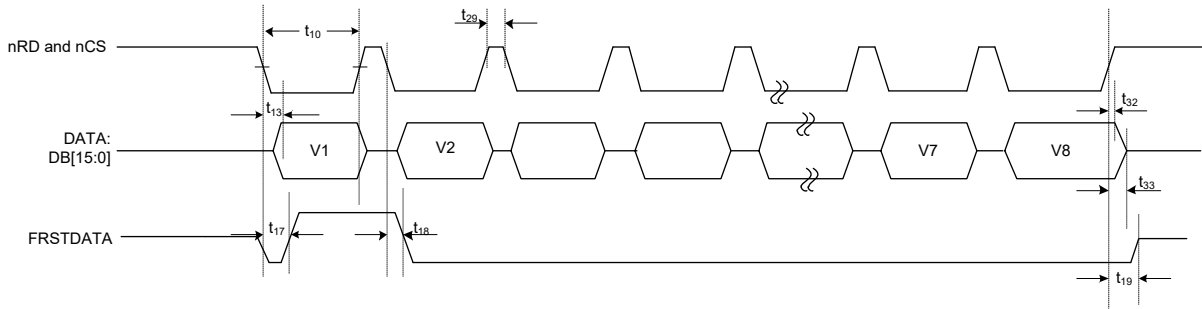


Figure 4. nCS and nRD, Linked Parallel Mode

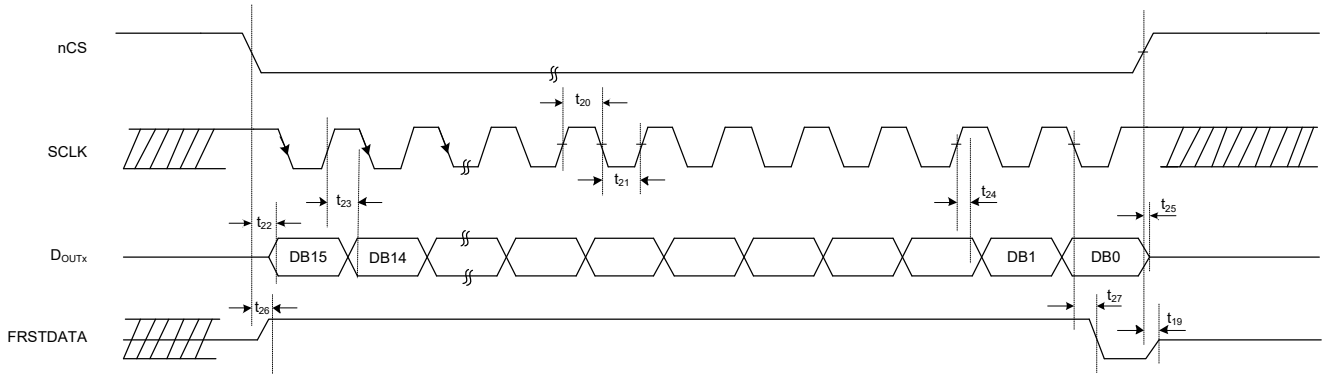


Figure 5. Serial Read Operation (Channel 1)

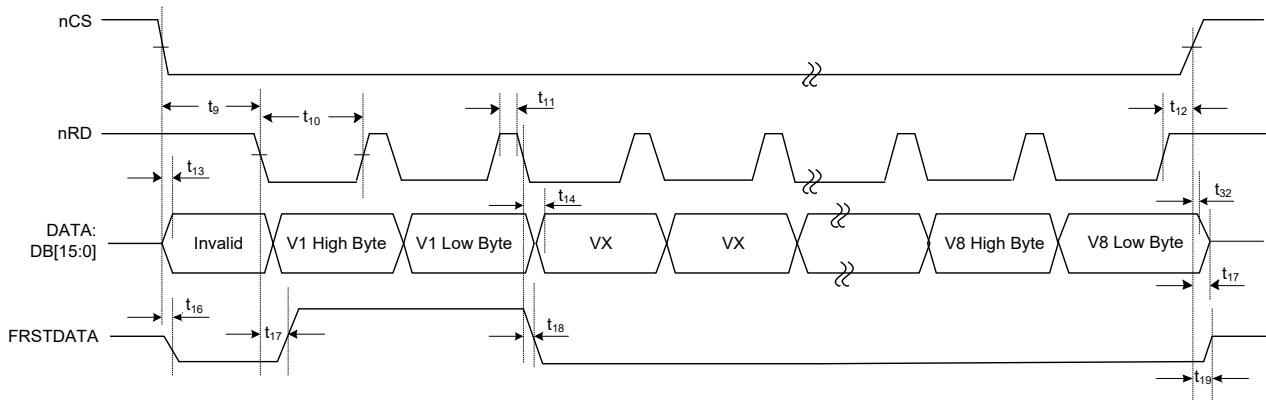
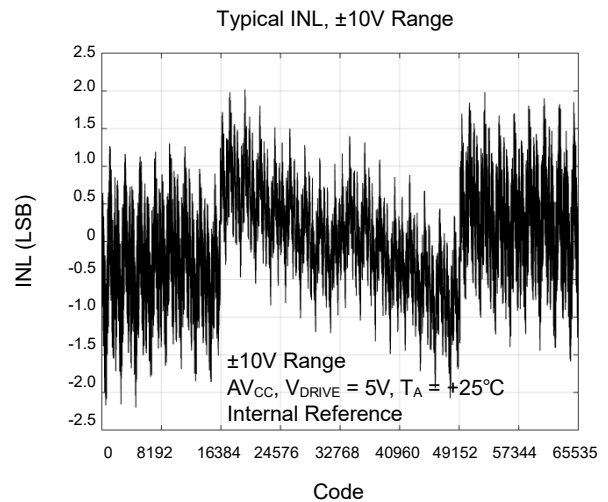
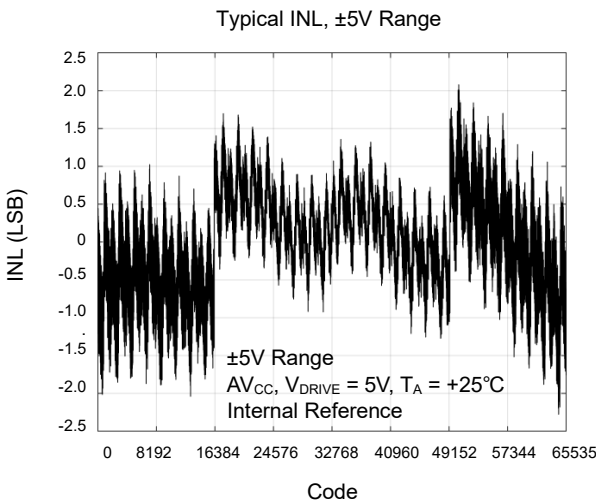
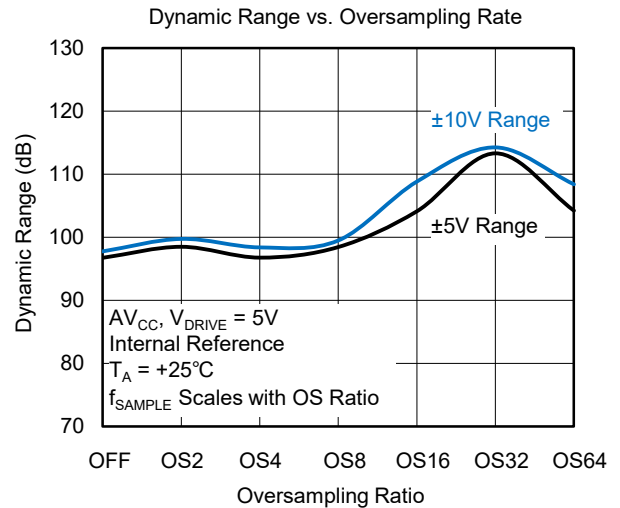
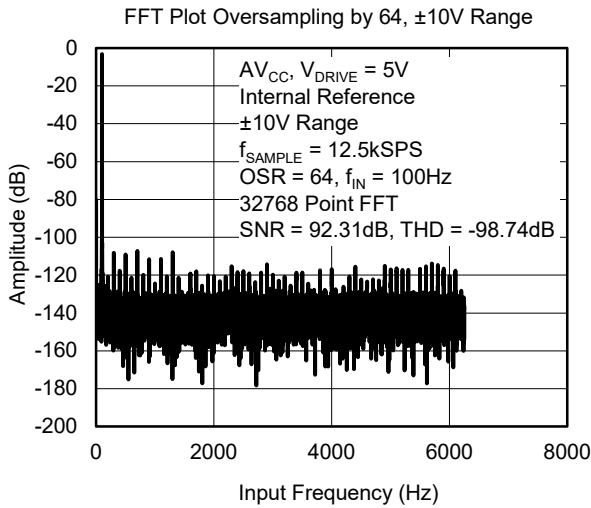
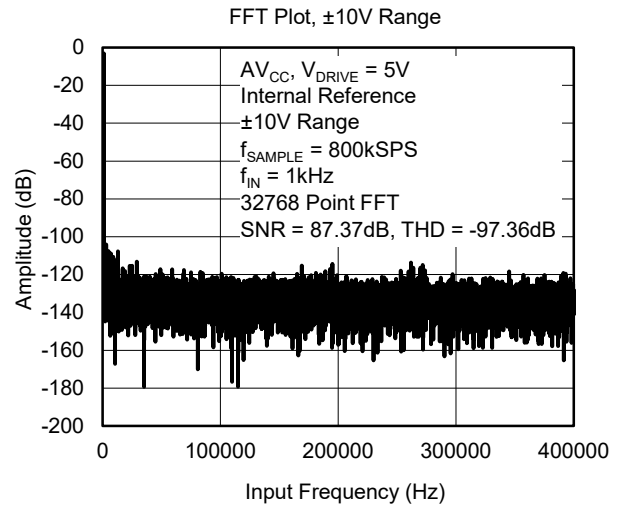
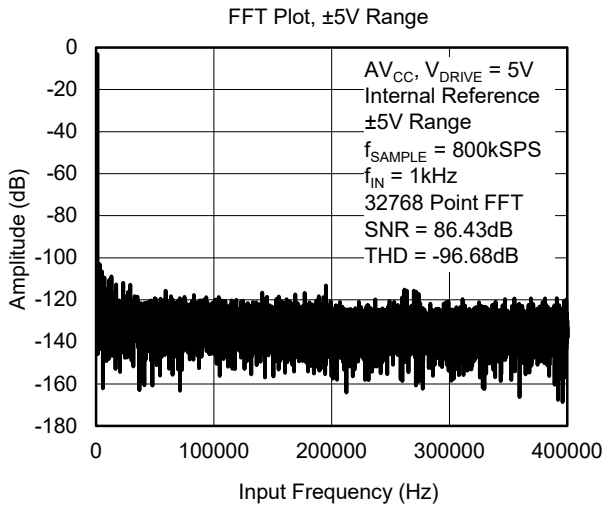
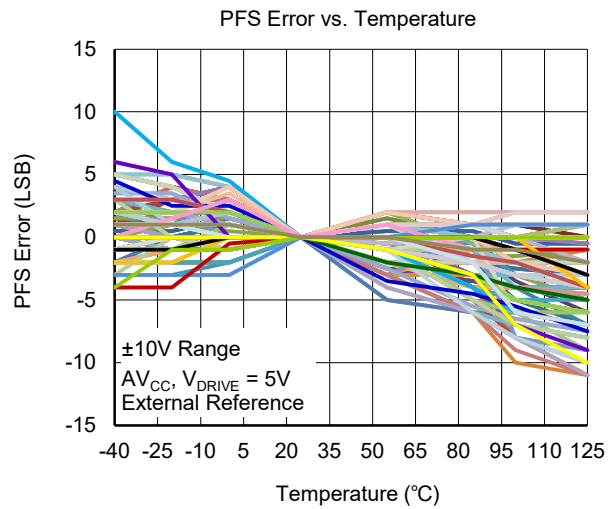
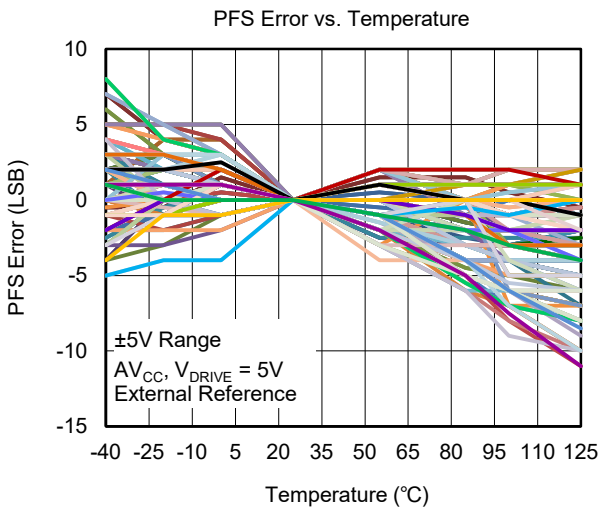
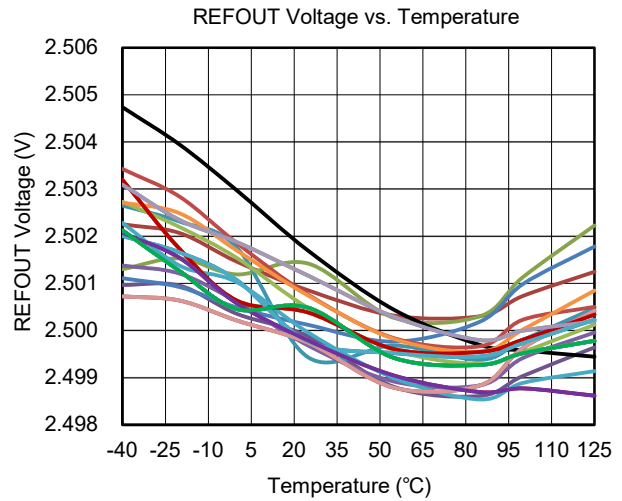
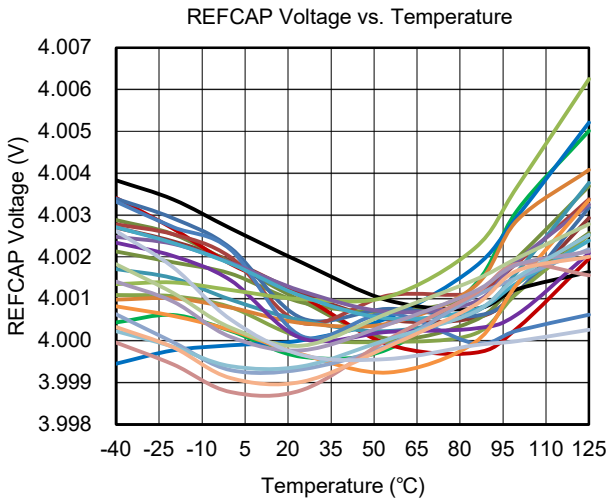
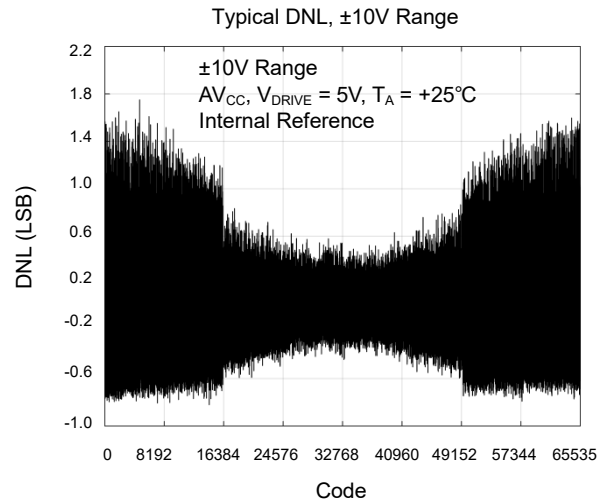
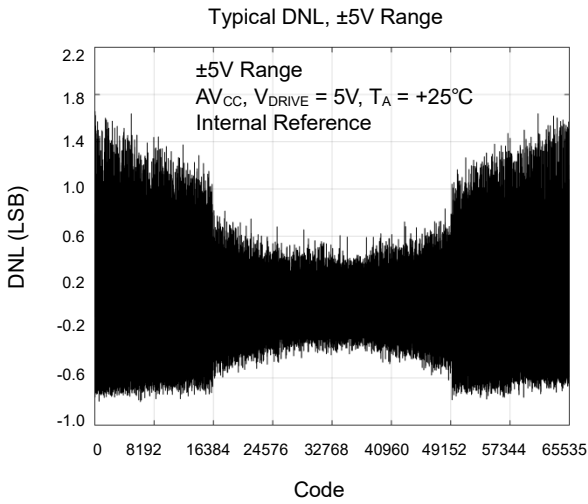


Figure 6. BYTE Mode Read Operation

TYPICAL PERFORMANCE CHARACTERISTICS

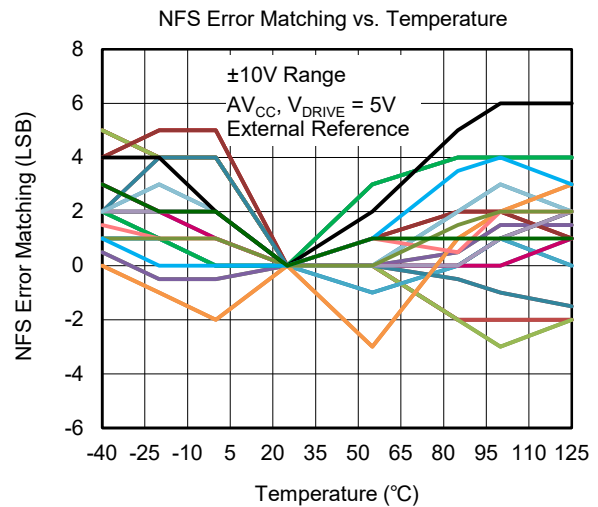
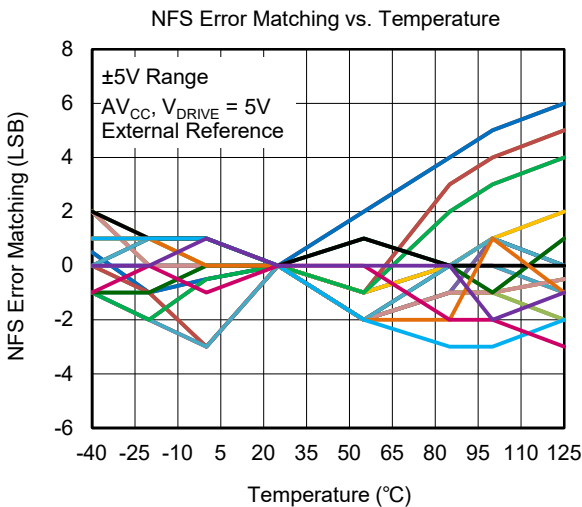
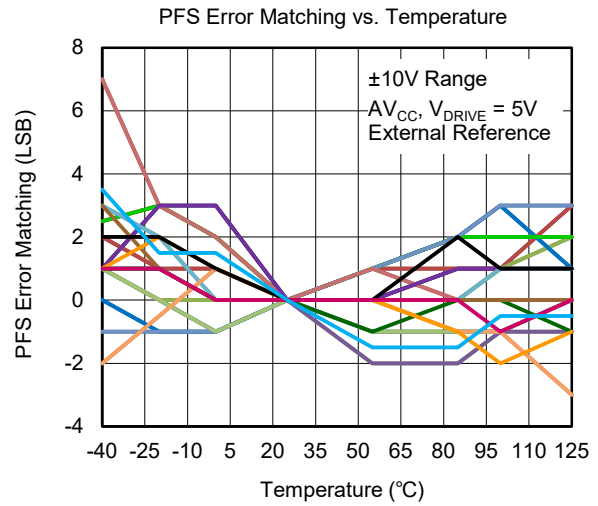
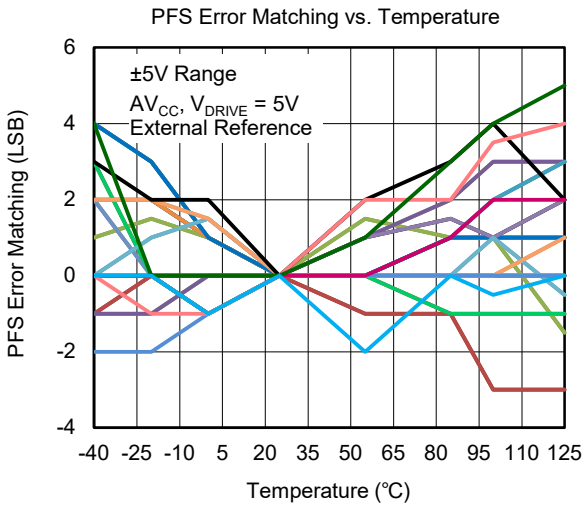
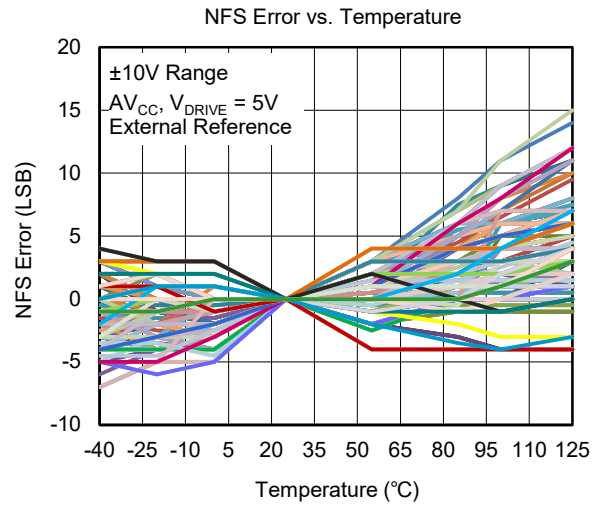
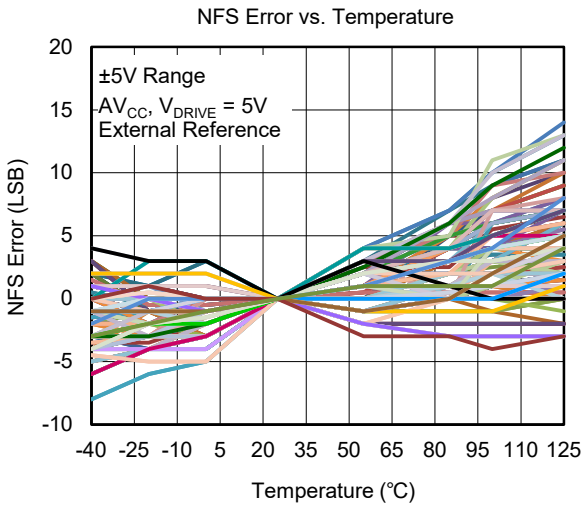


TYPICAL PERFORMANCE CHARACTERISTICS (continued)

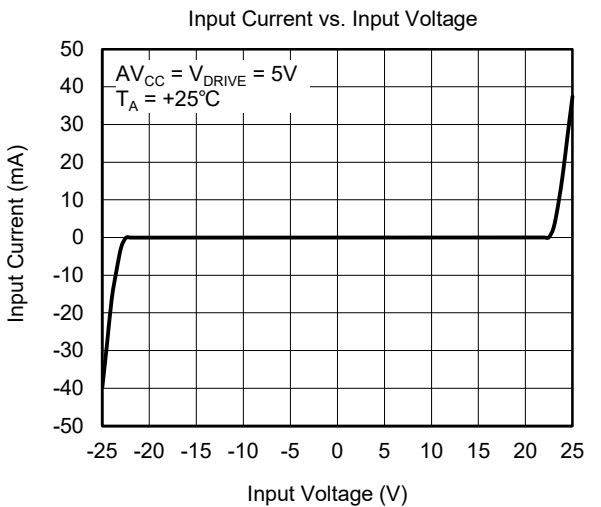
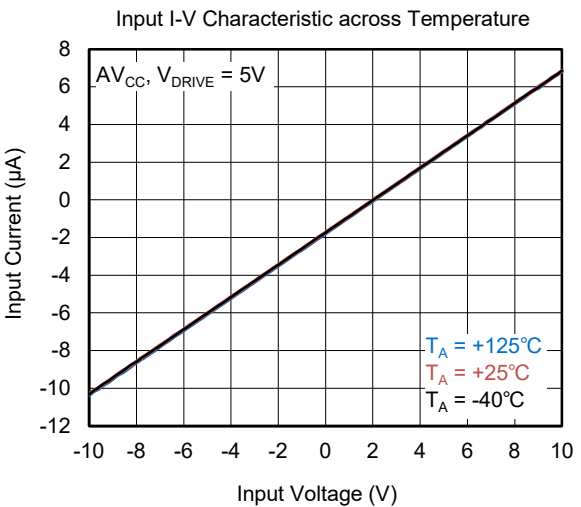
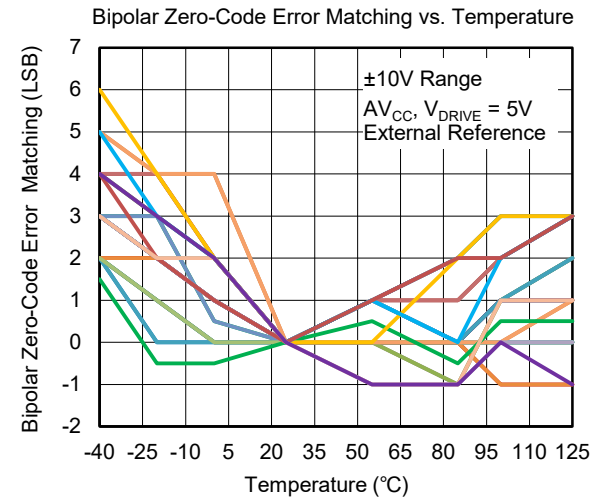
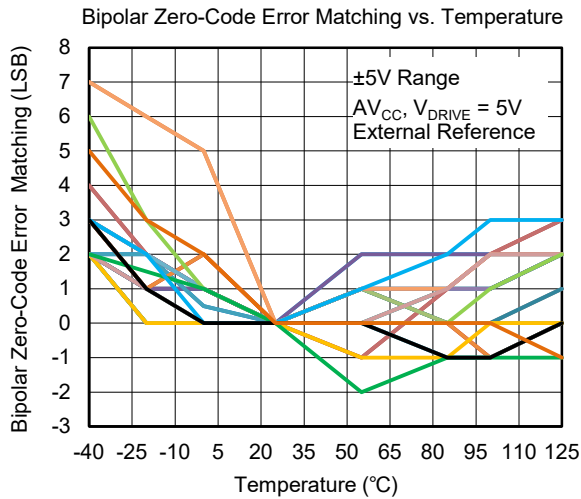
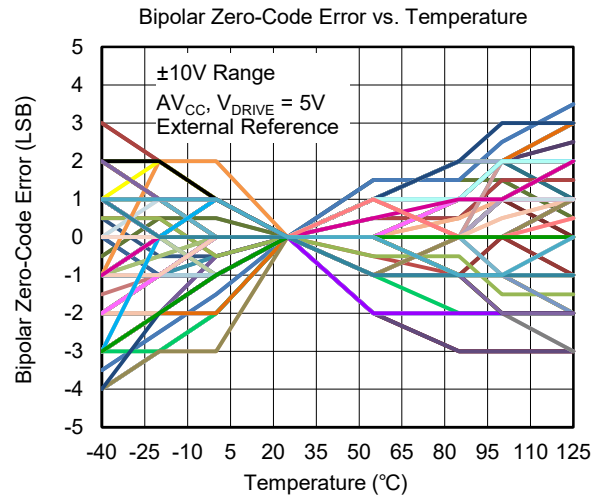
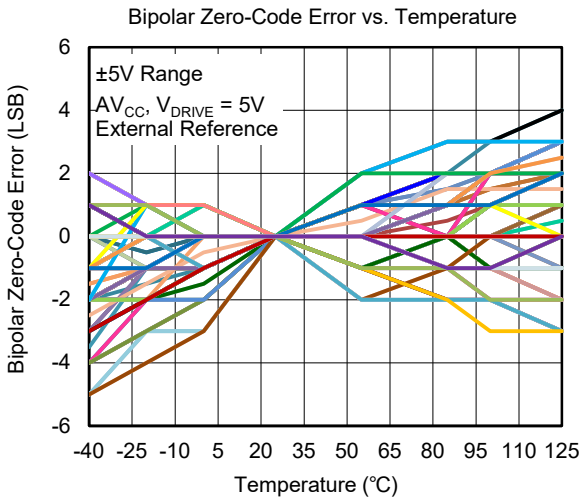




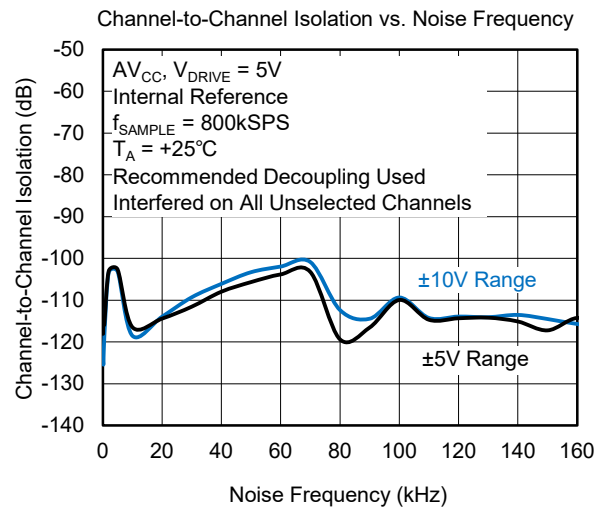
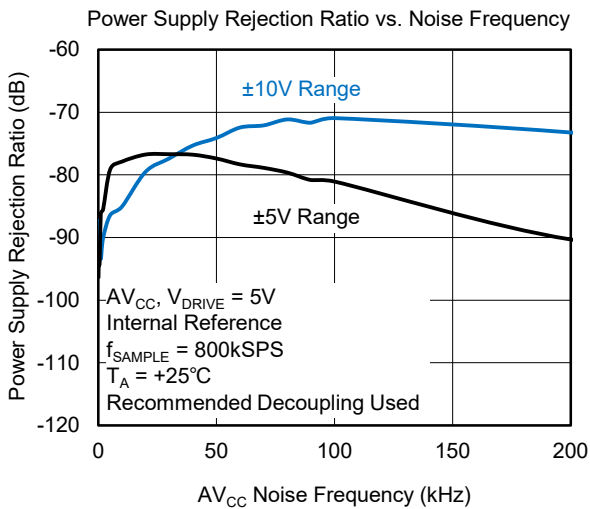
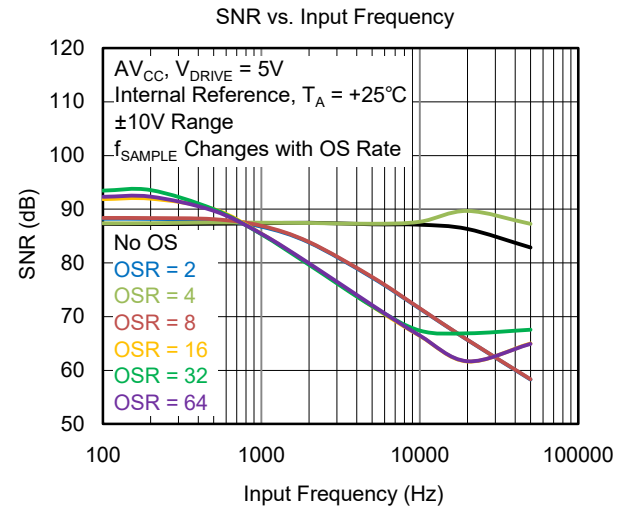
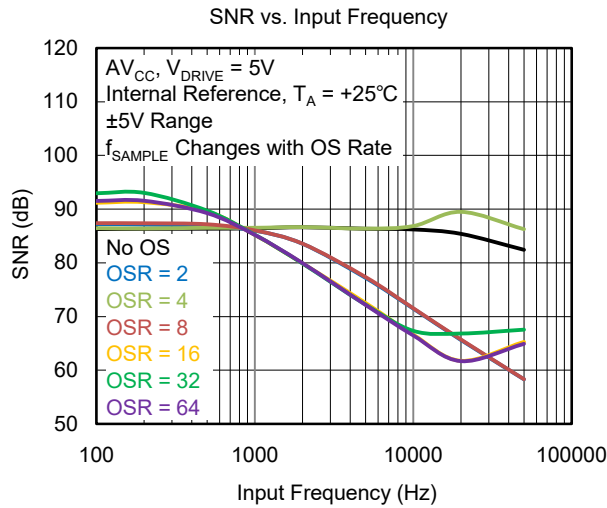
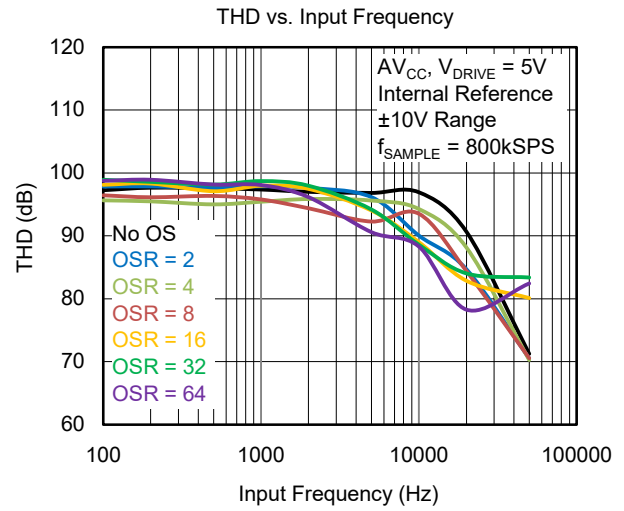
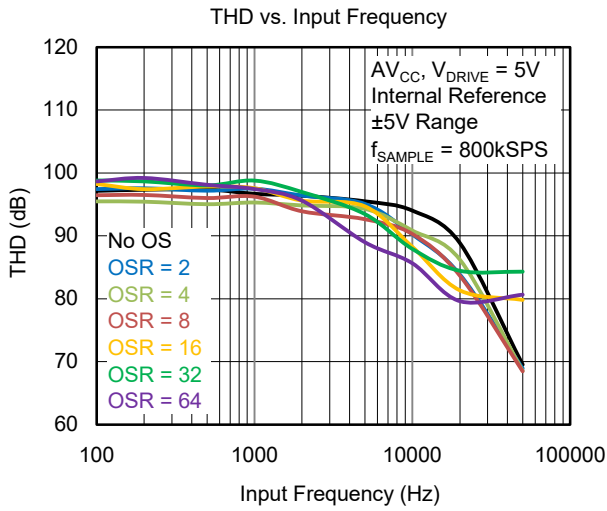
TYPICAL PERFORMANCE CHARACTERISTICS (continued)



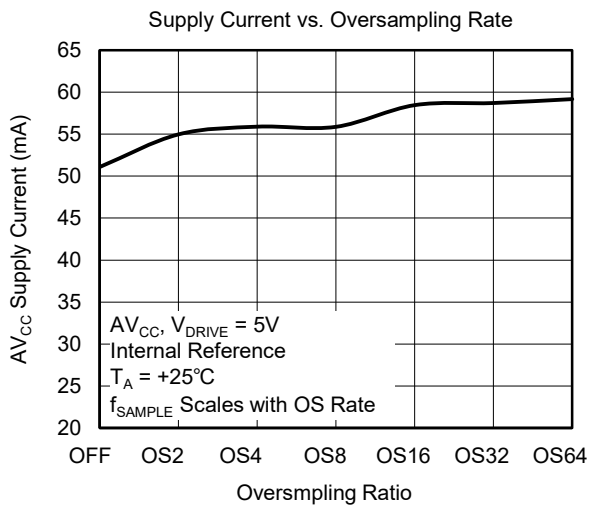
TYPICAL PERFORMANCE CHARACTERISTICS (continued)



TYPICAL PERFORMANCE CHARACTERISTICS (continued)



TYPICAL PERFORMANCE CHARACTERISTICS (continued)



FUNCTIONAL BLOCK DIAGRAM

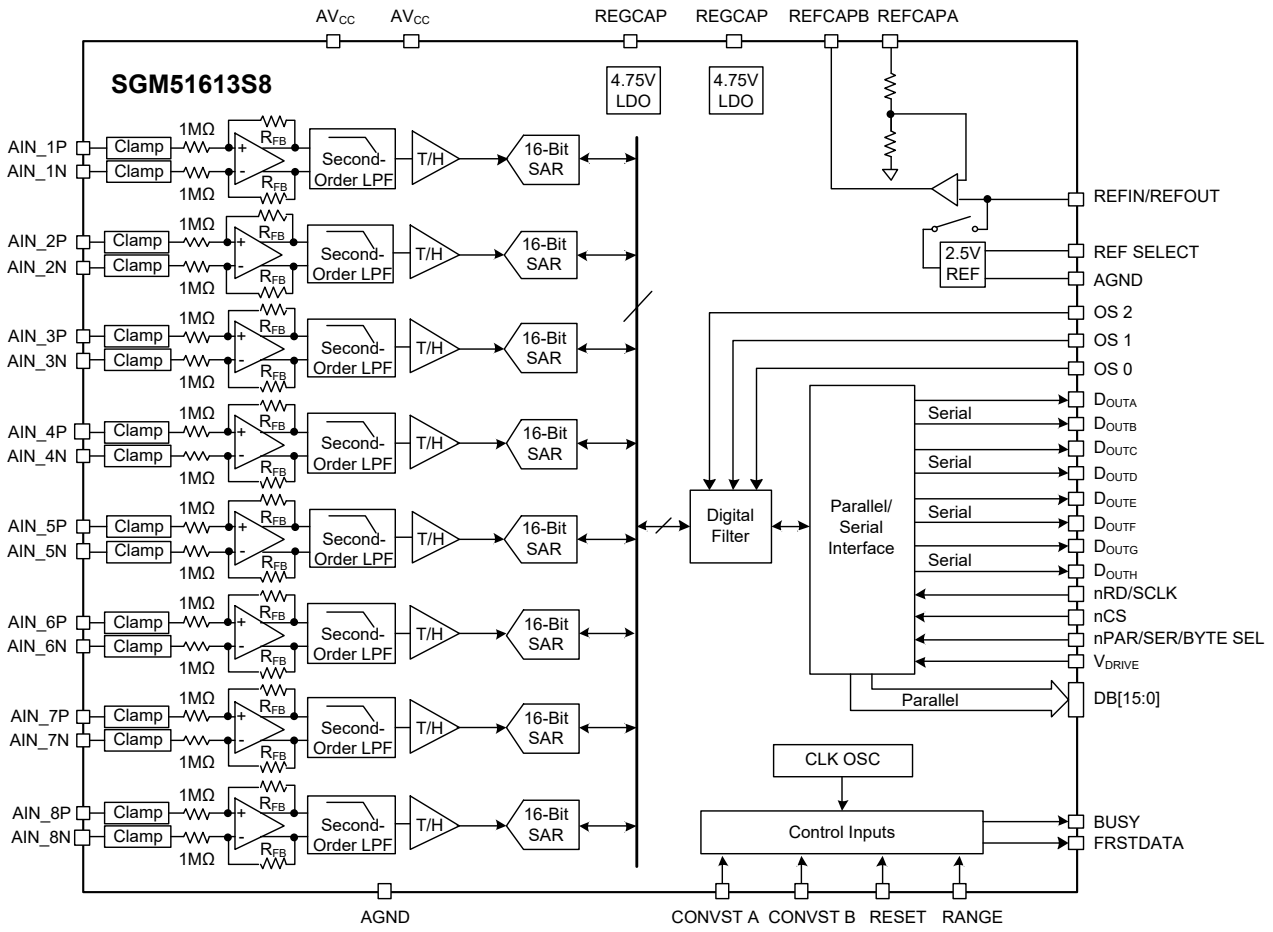


Figure 7. Block Diagram

# 8-Channel, 16-Bit, Bipolar Input Simultaneous Sampling ADC

## SGM51613S8

### DETAILED DESCRIPTION

#### Converter Details

The SGM51613S8 is a unipolar 5V supply SAR ADC. It supports true bipolar signal input. The device can perform all eight channels simultaneously sampling at speed of 800kHz.

#### Analog Input

##### Analog Input Ranges

The ADC input range is selected by setting the logic voltage of the RANGE pin. If the pin is set to logic high, the  $\pm 10V$  input range is selected for all channels. If the pin is set to logic low, the  $\pm 5V$  input range is selected for all channels.

It is suggested that the input range pin should be set by hardware pull-up or pull-down. After the system is powered up, a reset pulse must be issued to ensure that the input range is correctly set for all channels.

When in the power-down mode, it is recommended to connect the analog inputs to GND.

##### Analog Input Impedance

The input impedance of each channel is  $1M\Omega$ .

##### Analog Input Clamp Protection

The chip has the input over-voltage protection (OVP) circuit. Table 1 shows these characteristics.

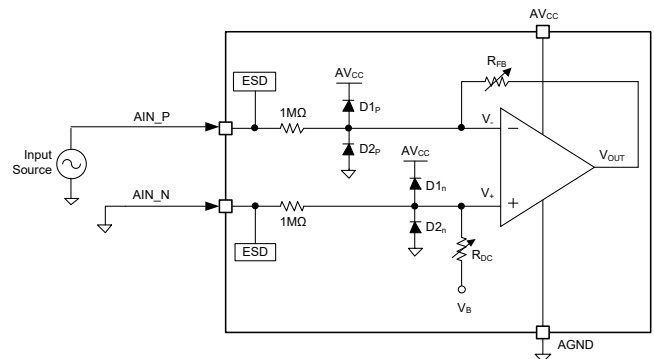
**Table 1. Input Over-Voltage Protection Limits when  $AV_{CC} = 5V$  <sup>(1)</sup>**

Input Condition ( $V_{OVP} = \pm 20V$ )	ADC Output	Comments
$ V_{IN}  <  V_{RANGE} $	Valid	Work normally.
$ V_{RANGE}  <  V_{IN}  <  V_{OVP} $	Saturated	ADC output is saturated, and the internal protection circuits are on.
$ V_{IN}  >  V_{OVP} $	Saturated	This may damage the chip.

NOTE:

1.  $AGND = 0V$ ,  $|V_{RANGE}|$  is the maximum input voltage for any selected input range, and  $|V_{OVP}|$  is the break-down voltage for the internal OVP circuit. Assume that  $R_S$  is approximately  $0\Omega$ .

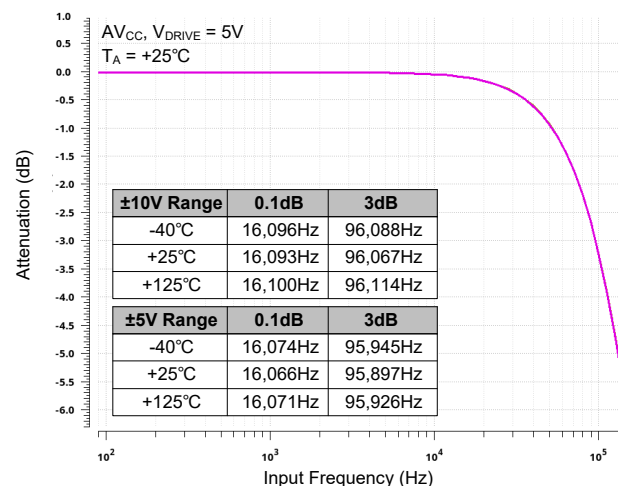
In the following condition, the input signal is applied before the analog  $AV_{CC}$  is powered on or the input signal is applied and keep analog  $AV_{CC}$  floating, the input OVP circuits will be on. And if the input voltage exceeds  $|V_{OVP}|$ , the chip may be damaged.



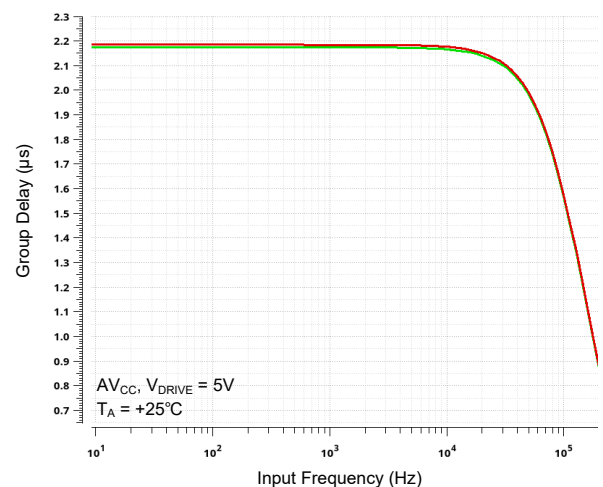
**Figure 8. Analog Input Equivalent Circuitry**

#### Analog Input Antialiasing Filter

The SGM51613S8 has an internal second-order low pass filter in front of ADC core. If  $\pm 5V$  input range is selected, the  $-3dB$  bandwidth is about 96kHz. If  $\pm 10V$  input range is selected, the  $-3dB$  bandwidth is about 96kHz.



**Figure 9. Analog Antialiasing Filter Frequency Response**



**Figure 10. Analog Antialiasing Filter Phase Response**

DETAILED DESCRIPTION (continued)

Track-and-Hold Amplifiers

This section briefly introduces how the device works and interfaces with the host controller.

Figure 11 shows the timing marks, there are three events T1 ~ T3.

- T1: On the rising edge of CONVST x, the input signals are simultaneously sampled by the device.
- T2: The device starts converting of all the input signals, the conversion is driven by internal clock.

T3: After all conversions are completed, the BUSY goes to low. On the following edge of BUSY, the device goes to tracking mode.

T4: On a new rising edge of CONVST x, a new conversion cycle is started.

ADC Transfer Function

The chip output code is in twos complement format. The ideal transfer function of SGM51613S8 is shown in Figure 12.

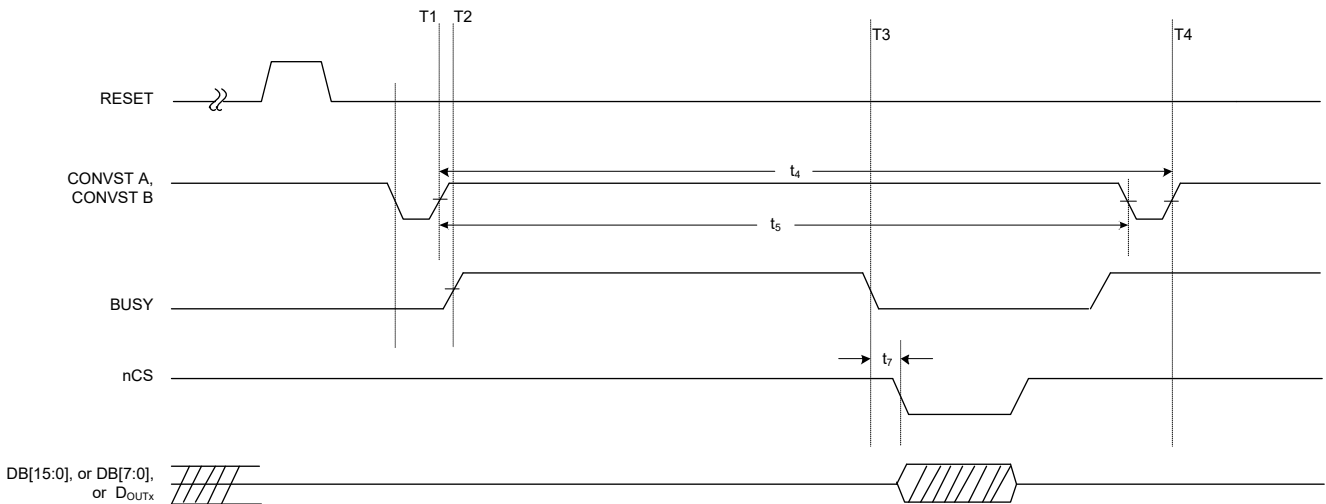
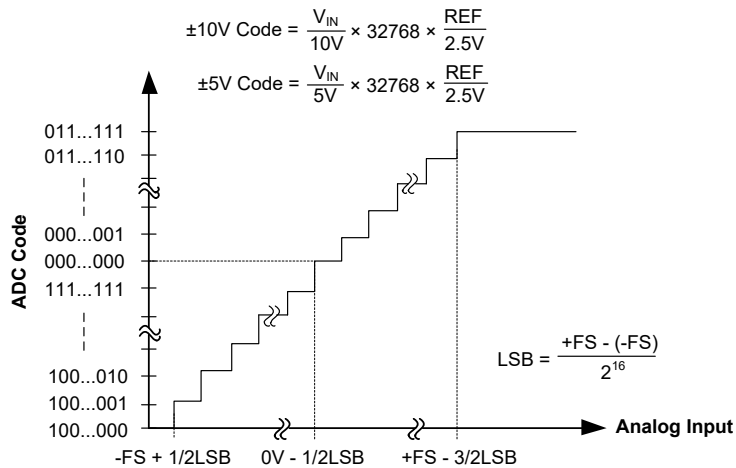


Figure 11. Timing Diagram of Device Operation



	+FS	Mid-Scale	-FS	LSB
±10V Range	±10V	0V	-10V	305µV
±5V Range	±5V	0V	-5V	152µV

NOTE: The LSB size depends on the selected analog input range.

Figure 12. SGM51613S8 Transfer Characteristics

DETAILED DESCRIPTION (continued)

Internal/External Reference

The SGM51613S8 has an internal 2.5V on-chip reference. It can work with internal reference or external reference. Using internal reference or external reference is decided by REF SELECT pin. When this pin is set to logic high, the internal reference is enabled. When this pin is set to logic low, the internal reference is disabled and an external 2.5V reference must be applied.

After a reset, the chip refreshes the reference selection status. It is decided by the REF SELECT pin setting.

For both the internal reference and the external reference, the chip needs decoupling capacitor on the REFIN/REFOUT pin. At the same time, the REFCAPA and REFCAPB must be tied together. And a typical decoupling 10µF capacitor must be applied between this pin and REFGND pin.

External Reference Mode

An external reference chip SGM4029-2.5 is used to drive three pieces of ADCs. A demo circuit connection is shown in Figure 13.

Internal Reference Mode

In a multi-chip system, one SGM51613S8 on-chip reference can be configured as output, the other chip can be configured as external reference input mode. A demo circuit connection is shown in Figure 14.

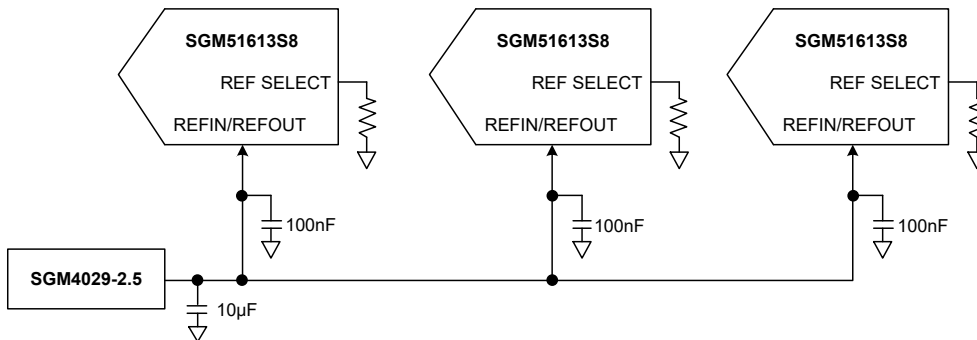


Figure 13. Single External Reference Driving Multiple SGM51613S8 REFIN Pins

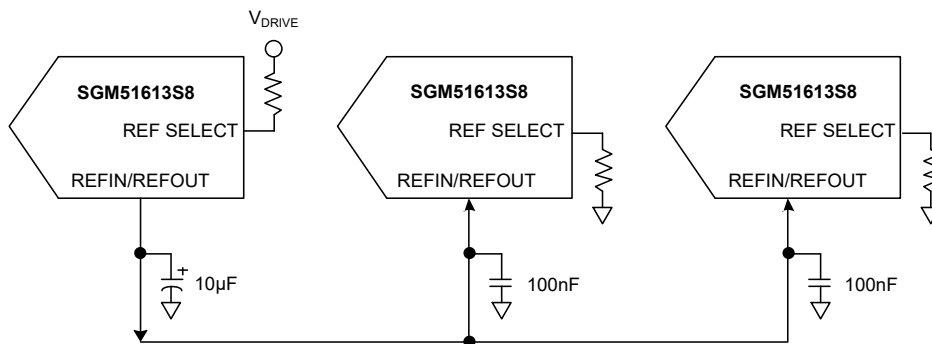


Figure 14. Internal Reference Driving Multiple SGM51613S8 REFIN Pins



DETAILED DESCRIPTION (continued)

Typical Connection Diagram

A typical connection circuit is shown in Figure 15. Note that all power supply pins and reference pins should be decoupled by the decoupling capacitors.

After the system is powered up, a reset should be issued to the chip to ensure all hardware setting is configured correctly.

Power-Down Modes

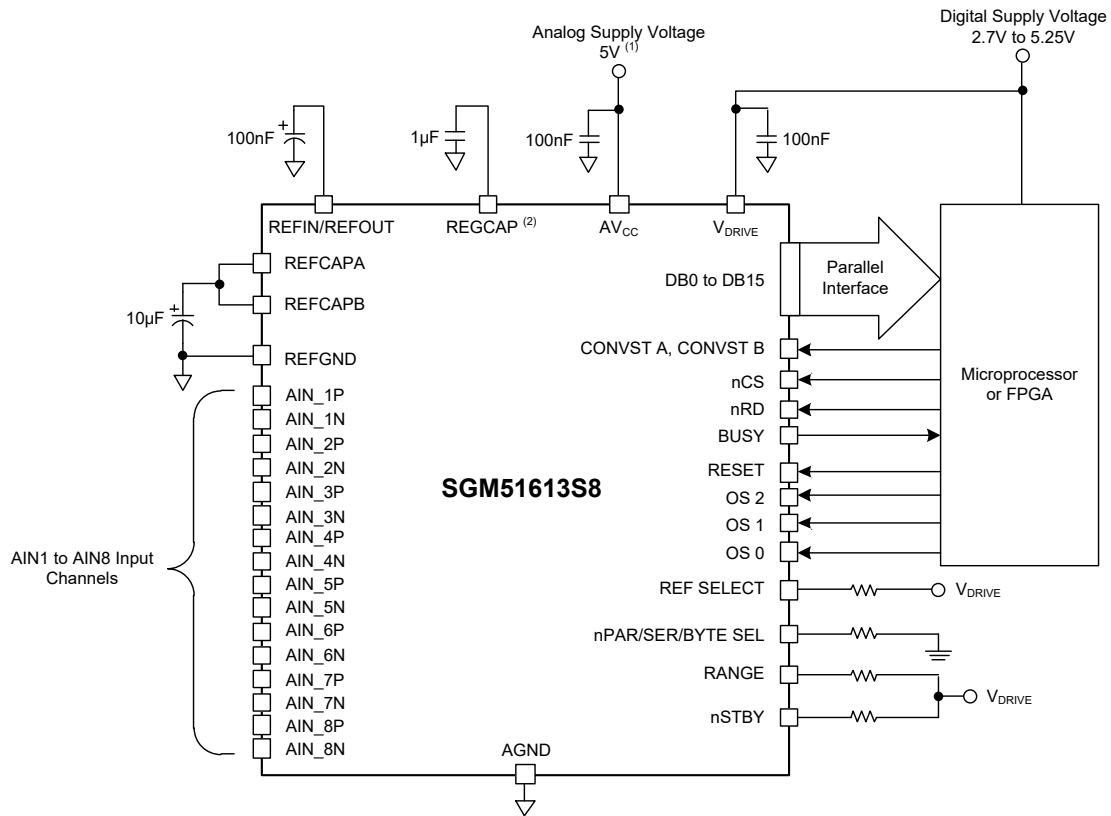
The SGM51613S8 supports two low power modes: standby mode and shutdown mode. Table 2 shows how to configure the chip into according mode.

In standby mode, the chip only powers down the input buffer amplifier and ADC core. The current consumption is about 8.9mA. To quit the standby mode, the wake-up time is about 200µs.

In shutdown mode, the chip powers down all the internal circuits. The current consumption is about 15µA. To quit the shutdown mode, a RESET signal must be applied. The wake-up time is about 23ms.

Table 2. Power-Down Mode Selection

Power-Down Mode	nSTBY	RANGE
Standby	0	1
Shutdown	0	0



- NOTES:
- At least one decoupling capacitor should be applied to each AV<sub>CC</sub> pin (pin 1, pin 37, pin 38, pin 48).
  - At least one decoupling capacitor should be applied to each REGCAP pin (pin 36, pin 39).

Figure 15. Typical Connection Diagram

DETAILED DESCRIPTION (continued)

Conversion Control

Simultaneous Sampling on All Analog Input Channels

To sample and convert all 8 input channels simultaneously, CONVST A and CONVST B can be tied together.

Simultaneously Sampling Two Sets of Channels

CONVST A controls the sampling and conversion of V1 to V4 channel. CONVST B controls the sampling and conversion of V5 to V8 channel.

In a conversion process cycle, after both CONVST A and CONVST B rising edges have been issued, then BUSY goes high indicates that ADC is doing conversion. The data readout is no different from the operating of CONVST A and CONVST B tied together.

Note that all unused input channels should be tied to system ground (AGND).

Digital Interface

The SGM51613S8 has three operating interface modes: parallel interface mode, serial interface mode and parallel byte interface mode.

Table 3. Interface Mode Selection

nPAR/SER/BYTE SEL	DB15	Interface Mode
0	0	Parallel interface mode
1	0	Serial interface mode
1	1	Parallel byte interface mode

Serial Interface (nPAR/SER/BYTE SEL = 1, DB15 = 0)

In serial interface mode, the SGM51613S8 has two options: eight serial data output pins mode (D<sub>OUTA</sub>, D<sub>OUTB</sub>, D<sub>OUTC</sub>, D<sub>OUTD</sub>, D<sub>OUTE</sub>, D<sub>OUTF</sub>, D<sub>OUTG</sub> and D<sub>OUTH</sub> output data simultaneously) and one serial data output pin mode (among all the options, D<sub>OUTA</sub>, D<sub>OUTB</sub>, D<sub>OUTC</sub>, D<sub>OUTD</sub>, D<sub>OUTE</sub>, D<sub>OUTF</sub>, D<sub>OUTG</sub> and D<sub>OUTH</sub>, D<sub>OUTA</sub> is preferred).

In serial operation mode, Figure 5 shows a demo operating timing diagram of reading one channel ADC data and framed by nCS. Table 4 shows the data output scheme in serial interface mode.

Table 4. Data Output Scheme in Serial Interface Mode

Pin	D <sub>OUTx</sub>	Output Data Sequence
24 - DB7/D <sub>OUTA</sub>	A	V1, V2, V3, V4, V5, V6, V7, V8
25 - DB8/D <sub>OUTB</sub>	B	V5, V6, V7, V8, V1, V2, V3, V4
27 - DB9/D <sub>OUTC</sub>	C	V3, V4, V5, V6, V7, V8, V1, V2
28 - DB10/D <sub>OUTD</sub>	D	V7, V8, V1, V2, V3, V4, V5, V6
19 - DB3/D <sub>OUTE</sub>	E	V2, V3, V4, V5, V6, V7, V8, V1
20 - DB4/D <sub>OUTF</sub>	F	V4, V5, V6, V7, V8, V1, V2, V3
21 - DB5/D <sub>OUTG</sub>	G	V6, V7, V8, V1, V2, V3, V4, V5
22 - DB6/D <sub>OUTH</sub>	H	V8, V1, V2, V3, V4, V5, V6, V7

Digital Filter

The SGM51613S8 has an internal configurable low pass digital filter. The oversampling rate is set by OS 2, OS 1 and OS 0 pins. OS 2 sets the MSB bit, OS 1 sets the middle weighting bit, and OS 0 sets the LSB bit. Table 5 shows the different available oversampling rates.

Once the OS x (OS 2, OS 1 and OS 0) pins setting are changed, the new setting will be latched on the falling edge of BUSY. And the new setting will take effect on the next conversion cycle. A demo time sequence is shown in Figure 16.

In the oversampling modes, CONVST A and CONVST B must be tied together to let ADC work correctly. The CONVST x (CONVST A and CONVST B) triggers the first conversion of each input channels in one conversion frame, the left conversions according to the oversampling rates will be triggered internally by ADC. For example, if the oversampling rate is set to 4, CONVST x triggers the first conversion and the left 3 times of conversions are triggered internally by ADC in one frame.

Refer to Table 5, while the oversampling rate is increased, the SNR is increased and the equivalent -3dB frequency bandwidth is decreased accordingly.

In Figure 16, for example, if the oversampling rate is increased by 2, the conversion time is increased by 2. To let the host controller has adequate time to read out the ADC conversion results, the total conversion cycle needs to be extended accordingly.

Note that the falling edge of BUSY is used to update ADC output data register by the ADC chip internally in Figure 16.

DETAILED DESCRIPTION (continued)

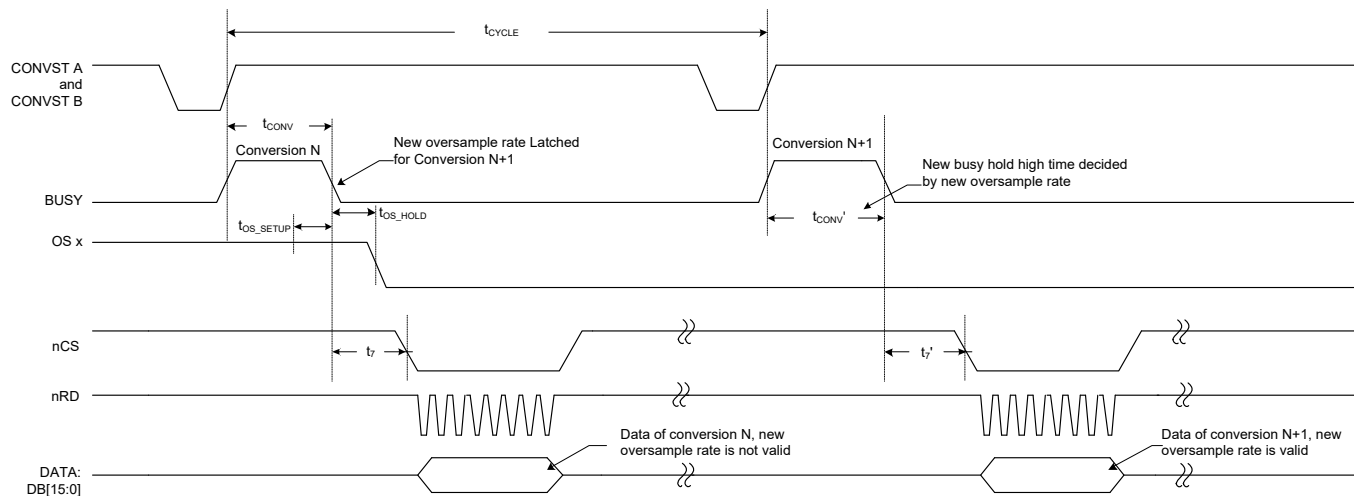


Figure 16. OS x Pin Timing

Table 5. Oversample Bit Decoding

OS[2:0]	OS Ratio	SNR 5V Range (dB)	SNR 10V Range (dB)	3dB BW 5V Range (kHz)	3dB BW 10V Range (kHz)	Maximum Throughput CONVST Frequency (kHz)
000	No OS	86.4	87.4	96	96	800
001	2	87.3	88.3	62.04	62.04	400
010	4	86.5	87.6	52.94	52.94	200
011	8	87.5	88.6	36.69	36.69	100
100	16	90.9	91.6	20.94	20.94	50
101	32	93.1	93.4	10.90	10.90	25
110	64	91.5	92.0	5.52	5.52	12.5
111	Invalid	—	—	—	—	—

DETAILED DESCRIPTION (continued)

The effect of oversampling on the code spread in a DC histogram plot is shown in Figure 17 to Figure 23. With the increase of the oversampling rate, the spread of the codes decreases.

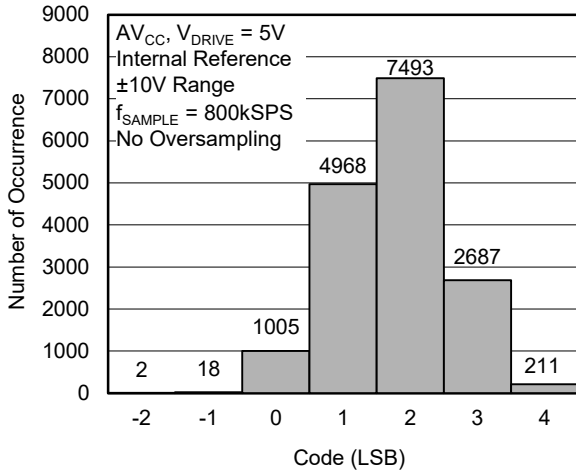


Figure 17. Histogram of Codes (No OS)

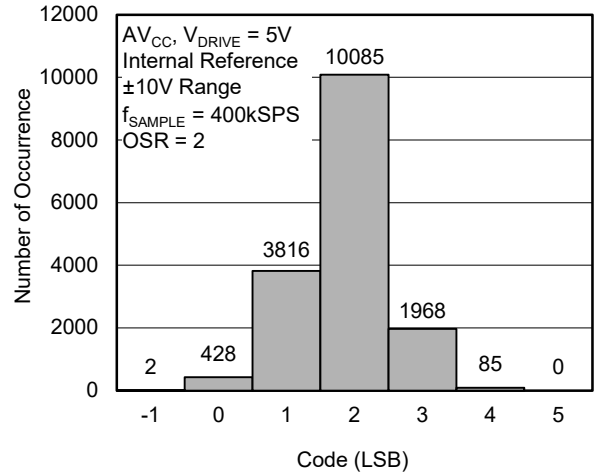


Figure 18. Histogram of Codes (OS x 2)

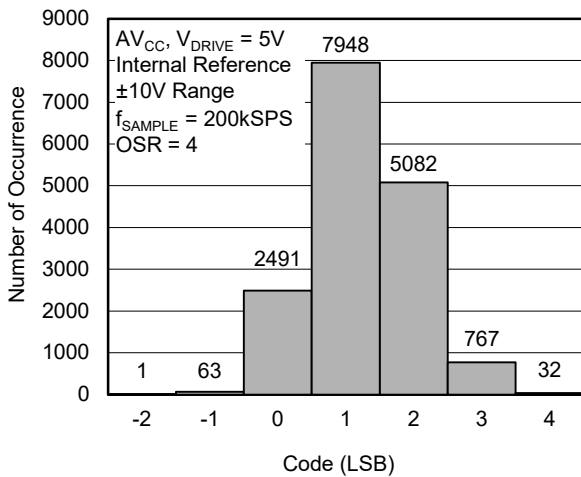


Figure 19. Histogram of Codes (OS x 4)

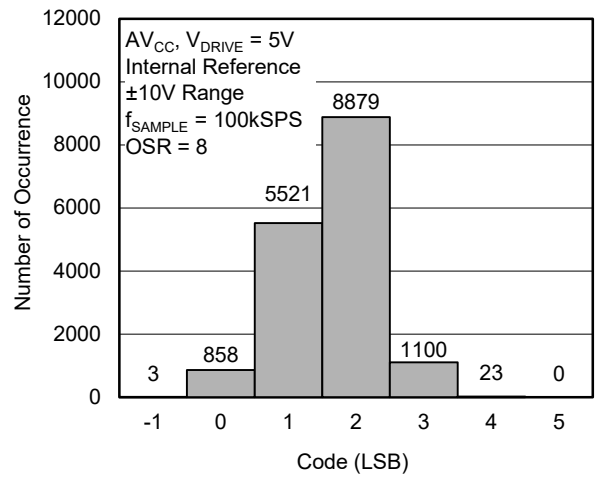


Figure 20. Histogram of Codes (OS x 8)

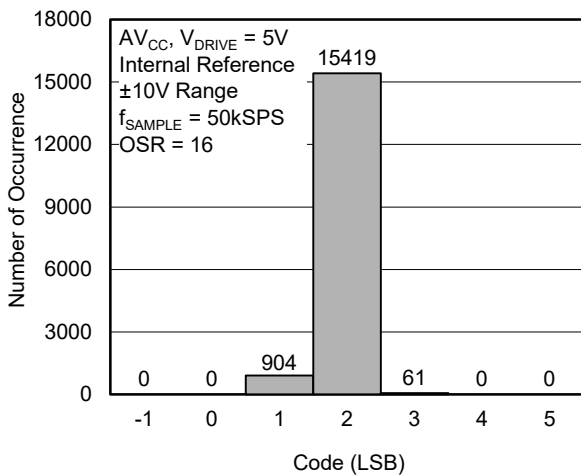


Figure 21. Histogram of Codes (OS x 16)

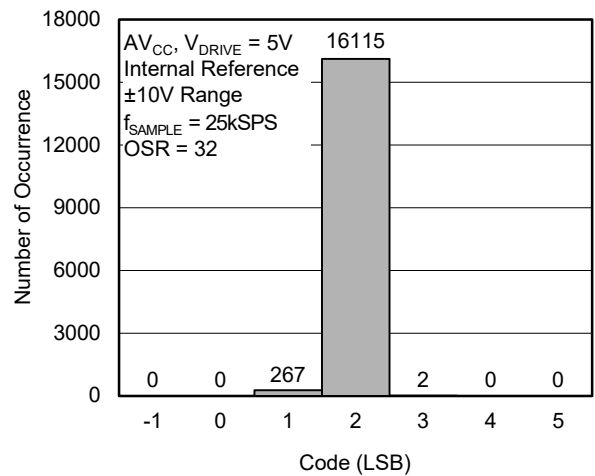


Figure 22. Histogram of Codes (OS x 32)

DETAILED DESCRIPTION (continued)

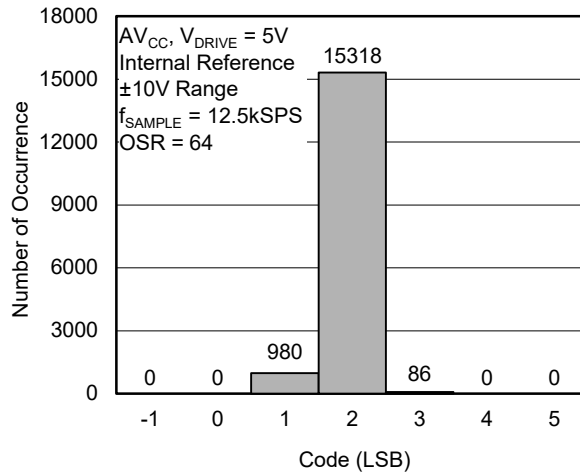


Figure 23. Histogram of Codes (OS x 64)

The digital filter frequency profiles for the different oversampling rates are shown in Figure 24 to Figure 29.

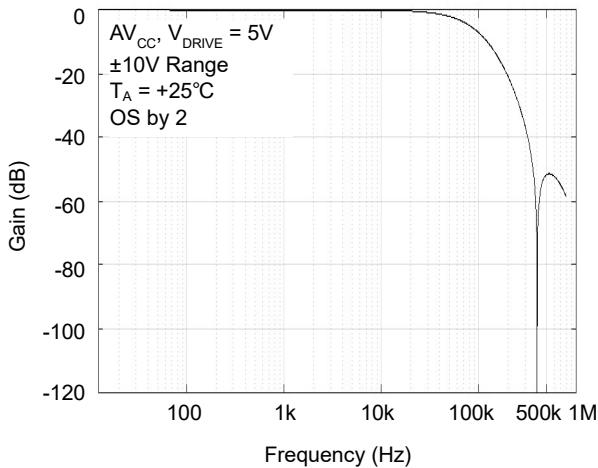


Figure 24. Digital Filter Response for OS 2

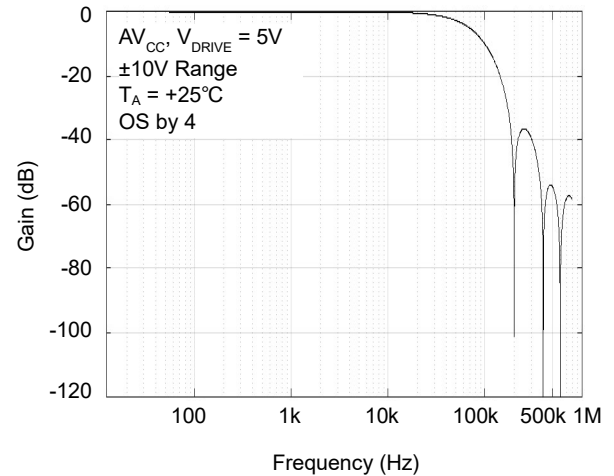


Figure 25. Digital Filter Response for OS 4

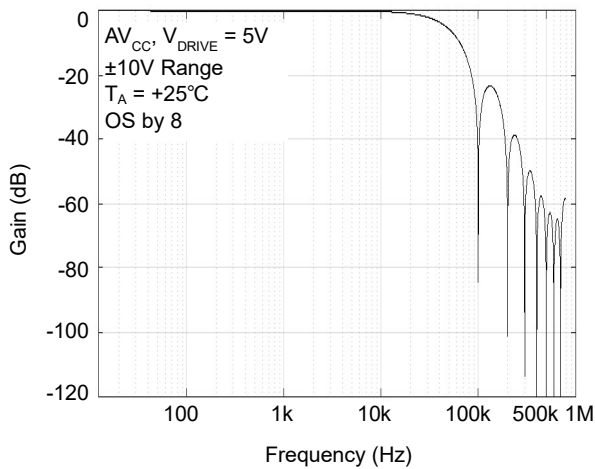


Figure 26. Digital Filter Response for OS 8

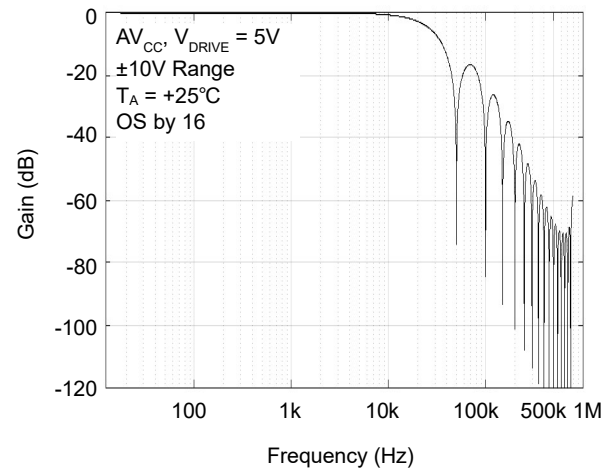


Figure 27. Digital Filter Response for OS 16

DETAILED DESCRIPTION (continued)

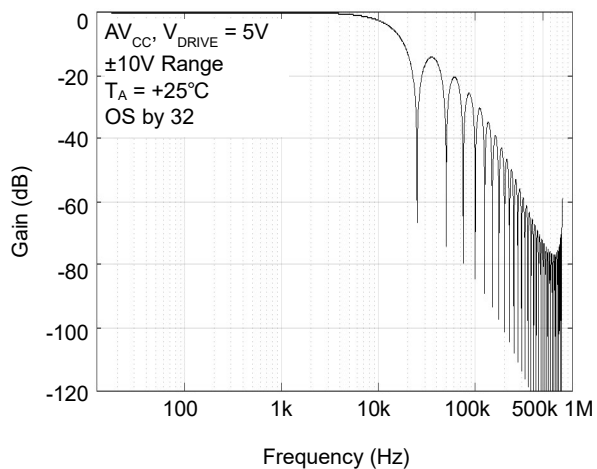


Figure 28. Digital Filter Response for OS 32

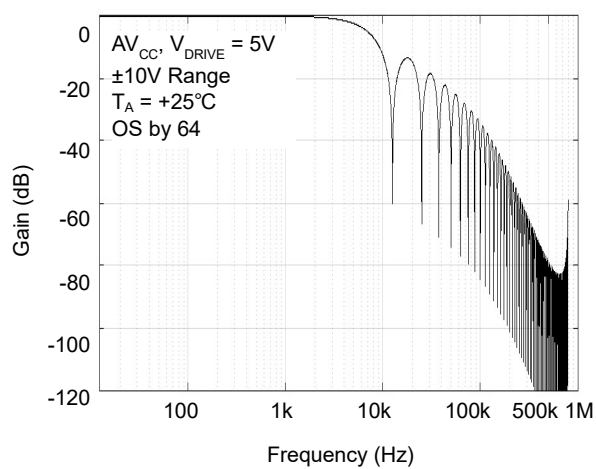


Figure 29. Digital Filter Response for OS 64

**REVISION HISTORY**

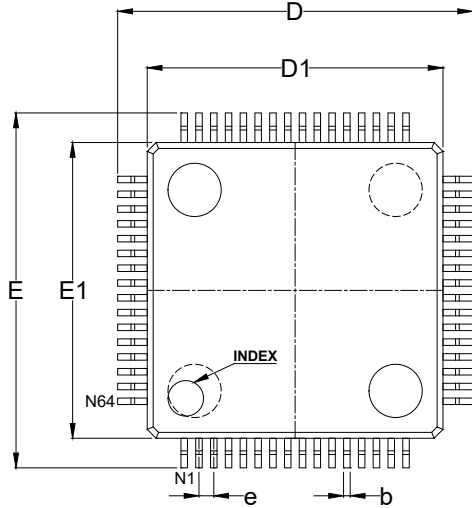
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

<b>Changes from Original (JUNE 2024) to REV.A</b>	<b>Page</b>
Changed from product preview to production data.....	All

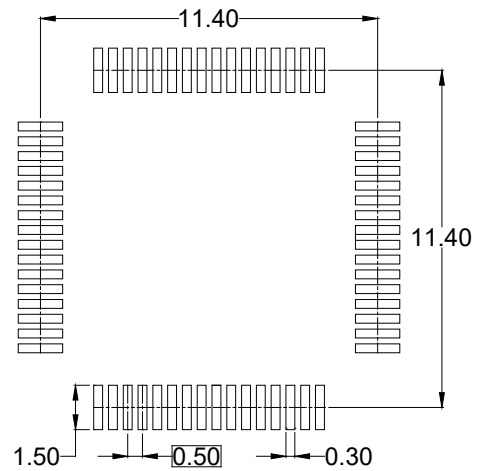
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PACKAGE OUTLINE DIMENSIONS

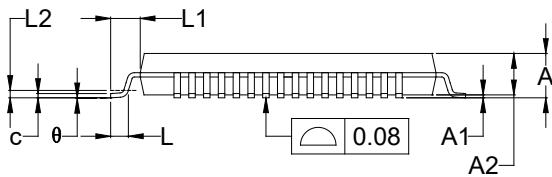
LQFP-10×10-64L



TOP VIEW



RECOMMENDED LAND PATTERN (Unit: mm)



SIDE VIEW

Symbol	Dimensions In Millimeters		
	MIN	MOD	MAX
A	-	-	1.600
A1	0.050	-	0.150
A2	1.350	1.400	1.450
b	0.170	-	0.270
c	0.090	-	0.200
D	11.800	-	12.200
D1	9.900	-	10.100
E	11.800	-	12.200
E1	9.900	-	10.100
e	0.500 BSC		
L	0.450	-	0.750
L1	1.000 REF		
L2	0.250 BSC		
θ	0°	-	7°

NOTES:

1. This drawing is subject to change without notice.
2. The dimensions do not include mold flashes, protrusions or gate burrs.
3. Reference JEDEC MS-026.



# PACKAGE INFORMATION

## TAPE AND REEL INFORMATION

### REEL DIMENSIONS



### TAPE DIMENSIONS



NOTE: The picture is only for reference. Please make the object as the standard.

### KEY PARAMETER LIST OF TAPE AND REEL

Package Type	Reel Diameter	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P0 (mm)	P1 (mm)	P2 (mm)	W (mm)	Pin1 Quadrant
LQFP-10×10-64L	13"	24.4	12.5	12.5	2.05	4.0	16.0	2.0	24.0	Q2

000001

# PACKAGE INFORMATION

## CARTON BOX DIMENSIONS



NOTE: The picture is only for reference. Please make the object as the standard.

## KEY PARAMETER LIST OF CARTON BOX

Reel Type	Length (mm)	Width (mm)	Height (mm)	Pizza/Carton
13"	386	280	370	5

DD0002